NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA (An Autonomous Institute)



Affiliated to

DR. A.P.J. ABDUL KALAM TECHNICAL UNIVERSITY, LUCKNOW



Evaluation Scheme & Syllabus

For

M. Tech in Mechanical Engineering (ME) First Year

(Effective from the Session: 2020-21)

NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA (An Autonomous Institute)

M.TECH (ME)

Evaluation Scheme

SEMESTER-I

S. N	Course Code	Subject	Po	eriod	s	Eva	aluation Schemes				and Nester	Total	Credit
		Theory	L	Т	Р	C T	T A	Tot al	PS	ТЕ	PE		
1	AMTME0101	Simulation Modelling and Analysis	3	0	0	20	10	30	-	70	-	100	3
2	AMTME0102	Design of Experiments	3	0	0	20	10	30	-	70	-	100	3
3	AMTCC0101	Research Process and Methodology	3	0	0	20	10	30	-	70	-	100	3
4		Departmental Elective – I*	3	0	0	20	10	30	-	70	-	100	3
5		Departmental Elective – II*	3	0	0	20	10	30	-	70	-	100	3
6	AMTME0151	simulation Modelling and Analysis lab	0	0	4	-	-		20	-	30	50	2
7	AMTME0152	Industry 4.0 Lab	0	0	4	-	-		20	-	30	50	2
		Total	15	0	8	-	-		-	-	-	600	19
	<u>(*) Refer tl</u>	<u>ne Electives list</u>											
			AMTME0111				Geometric Design & Rapid Prototyping						
	Departme	ntal Elective-I*	AMTME0112			12	Advanced Heat & Mass Transfer					fer	
	•		AN	1TM	E01 ⁻	13			Rene	wable	e Energ	y System	
			AN	1TM	E01 ⁻	14	Reliability, Maintenance Management & safety						t & safety
			٨N	1TM	E01 ⁻	15				Turbo	Mach	ines	
	Dopartma	ntal Elective-II*	٨N	1TM	E01 ⁻	16		Ad	lvanc	ed Me	chanic	al Vibratic	ons
	Departme		AMTME0117			17	7 Operations Research						
			AMTME0118 Advanced I.C. Engines										

NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA (An Autonomous Institute)

M.TECH (ME)

Evaluation Scheme

SEMESTER-II

				Evaluation Scheme					End			<u> </u>		
S · N	Course Code	Subject Po			Period	ls						nester	Total	Credit
		Theory		L	Т	Р	C T	T A	Tot al	PS	ТЕ	PE		
1	AMTME0201	Digital Mar Automation	nufacturing and n	3	0	0	20	10	30	-	70	-	100	3
2	AMTME0202	Composite	Materials	3	0	0	20	10	30	-	70	-	100	3
3		Departmen	tal Elective-III*	3	0	0	20	10	30	-	70	-	100	3
4		Departmen	tal Elective-IV*	3	0	0	20	10	30	-	70	-	100	3
5		Departmen	tal Elective-V*	3	0	0	20	10	30	-	70	-	100	3
6	AMTME0251	Automation Mechatron		0	0	4	-	-	-	20	-	30	50	2
7	AMTME0252	Composite	Materials Lab	0	0	4	-	-	-	20	-	30	50	2
8	AMTME0253	Seminar-I		0	0	2	-	-	-	50	-	-	50	1
		Total		15	0	10	-	-	-	-	-	-	650	20
			<u>(*) R</u>	<u>efe</u> i	• the	Elec	tives	s list	<u>t</u>					
			AMTME0211	I			Adv	vanc	ed Fir	nite E	lemer	nt Anal	ysis	
D	epartmental Ele	ctive-III*	AMTME0212	2	Modern Manufacturing Technology									
			AMTME0213	3	Advanced Welding Technology									
			AMTME0214	ł	Computational Fluid Dynamics									
			AMTME021	5	Advanced Mechanics of Solids									
Г	Departmental Ele	ctive-IV/*	AMTME021	6	Optimization Techniques									
			AMTME021	7	Artific	ial Int	ellige	nce a	ind Ma	achine	Learn	ning(All	ML)	
	AMTME0218						Ma	anag	emen	t Infor	matio	on Syst	tem	
			AMTME0219	9			F	lexib	le Ma	nufac	turing	g Syste	m	
г	Departmental Elective-V*			0					Mad	chine	Visior	٦		
		5011VG- V	AMTME022	1			Ra	pid I	Manuf	actur	ing ar	nd Too	ling	
			AMTME0222	2				Hyb	rid Ve	hicle	Tech	nology	1	

		M. TECH FIRST YEAR			
Course	Code		Т	Р	Credit
Course		Simulation, Modelling & Analysis 3	0	0	3
		asic of Mechanical Engineering, Electrical Engineering, Dif	fere	ntiation	Integration
			lerer	manoi	i, integration
	e objective	e: I learn about the need of simulation and different statis	tical	mada	1
		l learn about Queue model.	lical	mode	
		l learn about random number generation.			
		l learn about different features of MATLAB			
		l learn about Bond graph			
5 5		Course Contents / Syllabus			
UNIT-I	T T	ntroduction			09 hours
		n: a tool, advantages and disadvantages of simulation, areas o	f apr	lication	
		mponents of a system, discrete and continuous systems, discret			
		ncepts in discrete event simulation. Models in Simulation: T			
		uing systems; inventorysystems; reliability and maintainability			
		distribution;Binomial distribution; Geometric distribution, contin distribution, Exponential Growth & Decay model, Logistic mode		distrib	ution: Uniform
UNIT-I	_	Queuing Models and Random Numbers			8hours
		haracteristics of queuing systems, the calling population,	evete	m car	
		anism, queuing notations, long run measures of performa			
1 ,				1 9400	ang by brennb,
	lization in G/	$/G/1/\infty/\infty$ queues.			
		$/G/1/\infty/\infty$ queues. neration: Properties of random numbers, Pseudo random	num	bers, 1	techniques of
Random 2	Number Ger	$/G/1/\infty/\infty$ queues. neration: Properties of random numbers, Pseudo random mbers, tests of random numbers	num	bers, 1	techniques of
Random generating	Number Ger g random nur	neration: Properties of random numbers, Pseudo random			
Random generating Random	Number Ger g random nur Variate Gen	neration: Properties of random numbers, Pseudo random mbers, tests of random numbers			
Random generating Random	Number Ger g random nur Variate Gen al distribution	neration: Properties of random numbers, Pseudo random mbers, tests of random numbers neration: Inverse transform technique, Direct transformation			Normal and
Random generating Random Lognorma UNIT-I	Number Ger g random nur Variate Gen al distribution	neration: Properties of random numbers, Pseudo random mbers, tests of random numbers neration: Inverse transform technique, Direct transformation, Convolution Method, Acceptance rejection technique	on f	or the	Normal and
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		M. TECH FIRST YEA	AR					
Course	Code	AMTME0102]	L	Т	Р	Credit	_
Course		Design of Experiments	3	3	0	0	3	
		Basics of statics						
	objectiv							_
Course		e objective is to learn how to plan, design	and conduct e	vn	erii	nent	efficient	V
1	and effect		and conduct c	лр	UT II	nonu	, ennerenti	y
2		tive is to analyze the resulting data to obtain	n objective con	clu	sio	ns.		
3	The objec	tive of the Taguchi's method is to produce	e high quality	pro	du	ct at	low cost t	0
	the manuf				1		• •	
4		tive of Signal-to-noise ratio is a measure u				engii	neering the	ıt
	compares	the level of a desired signal to the level of b	background not	lse.				
		Course Contents / Sylla	bus					
UNIT-	I In	ntroduction					09 hour	'S
		ntation, Typical applications of Experimental						
		ts. Concepts of random variable, probability, of population, Measure of Central tendency; 1						
		f confidence level.	weath meetian a	ina	III	ac,	vicasures c	'1
UNIT-	II E	xperimental design					8hour	S
		: Terminology: factors, levels, interactions, treat						
		signs for two factors and three factors. Three-le						
and three composite		ctor effects, Factor interactions, Fractional factor	orial design, Sa	tura	ited	Des	gns, Centra	ıl
composite	ucsigns							
-	-	nalysis and Interpretation Methods					09 hour	<u> </u>
UNIT-	III A	nalysis and Interpretation Methods	Plotting metho	bd	An	alvsis	09 hour	
UNIT- Measures	of variabilit	nalysis and Interpretation Methods ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV					of varianc	e
UNIT-I Measures (ANOVA) models fro	of variabilit of ractoria om experime	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data	VA, Regression	an	aly		of varianc Aathematica	e al
UNIT- Measures (ANOVA) models fro UNIT-	of variabilit in Factoria om experime IV E	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data xperiment Design Using Taguchi's Or	vA, Regression	an ray	aly ys	sis, N	of varianc Aathematica 08 hour	e al 'S
UNIT- Measures (ANOVA) models fro UNIT- Types of C	IIIAof variabilitin Factoriaom experimeIVEOrthogonal A	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data xperiment Design Using Taguchi's Or Arrays, selection of standard orthogonal arrays, I	VA, Regression thogonal Ar linear graphs and	an ray	aly ys	sis, N	of varianc Aathematica 08 hour	e al 'S
UNIT- Measures (ANOVA) models fro UNIT- Types of C Dummy le	IIIAof variabilitin Factoriaom experimeIVEOrthogonal Aevel Techniq	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data xperiment Design Using Taguchi's Or Arrays, selection of standard orthogonal arrays, I ue, Compound factor method, Modification of I	VA, Regression thogonal Ar linear graphs and	an ray	aly ys	sis, N	of varianc Aathematica 08 hour assignmen	ee al ' S t,
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UNIT- Measures (ANOVA) models fro UNIT-J Types of C Dummy le UNIT-Y Evaluation	IIIAof variabilit) in Factoriaom experimeIVEOrthogonal Aevel TechniqVSin of sensitivi	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data xperiment Design Using Taguchi's Or Arrays, selection of standard orthogonal arrays, I ue, Compound factor method, Modification of I	VA, Regression thogonal Ar linear graphs and inear graphs blems: Smaller-t	an ray d In	aly ys tera	sis, N action	of varianc Aathematica 08 hour assignmen 08 hour be, Nomina	re al rs t, rs 1-
UNIT- Measures (ANOVA) models fro UNIT- Types of C Dummy le UNIT- Evaluation the –better	IIIAof variabilit) in Factoriaom experimeIVEDrthogonal Aevel TechniqVSin of sensitivir-type, Large	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data xperiment Design Using Taguchi's Or Arrays, selection of standard orthogonal arrays, I uue, Compound factor method, Modification of I ignal to Noise Ratio ity to noise. Signal to Noise ratios for static prob	VA, Regression thogonal Ar linear graphs and inear graphs blems: Smaller-t	an ray d In	aly ys tera	sis, N action	of varianc Aathematica 08 hour assignmen 08 hour be, Nomina	re al rs t, rs 1-
UNIT- Measures (ANOVA) models fro UNIT- Types of C Dummy le UNIT- Evaluation the -better arrays, par Textbo	IIIAof variabilitin Factoriaom experimeIVEOrthogonal Aevel TechniqVSin of sensitivir-type, Largecameter desigoks:	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data xperiment Design Using Taguchi's Or Arrays, selection of standard orthogonal arrays, I jue, Compound factor method, Modification of I ignal to Noise Ratio ity to noise. Signal to Noise ratios for static prob er-the-better type. Parameter and tolerance des gn strategy, tolerance design strategy	VA, Regression thogonal Ar linear graphs and inear graphs blems: Smaller-t ign concepts, Ta	an ray d In he- agu	aly ys tera bett	sis, M action cer typ c's inr	of varianc Aathematica 08 hour assignmen 08 hour be, Nomina er and oute	re al rs t, rs l- er
UNIT- Measures (ANOVA) models fro UNIT- Types of C Dummy le UNIT- Evaluation the -better arrays, par Textbo D.C. Mont	IIIAof variabilitin Factoriaom experimeIVEOrthogonal Aevel TechniqVSin of sensitivir-type, Largecameter desigoks:	ty, Ranking method, Column effect method & al Experiments: YATE's algorithm for ANOV ental data xperiment Design Using Taguchi's Or Arrays, selection of standard orthogonal arrays, I uue, Compound factor method, Modification of I ignal to Noise Ratio ity to noise. Signal to Noise ratios for static prob er-the-better type. Parameter and tolerance des	VA, Regression thogonal Ar linear graphs and inear graphs blems: Smaller-t ign concepts, Ta	an ray d In he- agu	aly ys tera bett	sis, M action cer typ c's inr	of varianc Aathematica 08 hour assignmen 08 hour be, Nomina er and oute	re al rs t, rs l- er
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		M. TECH FIRST YEAR					
Course	Code	AMTCC0101	L	Т	Ρ	Cred	it
Course	Title	Research Process & Methodology	3	0	0	3	
Course	object	ive:					
1	To und	lerstand the concept / fundamentals of research and thei	ir ty	pes			
2	To und	erstand the methods of research design and steps of rese	earc	:h p	roces	s	
3	To und	erstand the methods of data collection and procedure of	sar	npli	ng te	chniqu	es
4		yse the data, apply the statistical techniques and underst	tan	d th	e con	cept o	f
		esis testing					
5		erstand the types of research report and technical writing	g.				
Pre-rec	luisites	Basics of Statistics					
	т	Course Contents / Syllabus Introduction to Research				0	I
UNIT							hours
		tive and motivation of research, Types and approaches of					
•	· • •	lied vs. Fundamental, Quantitative vs. Qualitative, (npirical,
UNIT		ls versus Methodology, significance of research, criteria o Research Formulation and Design	of go	ood	resea		hours
		s and steps involved, Definition and necessity of research	h	-ahl			
	.	rature review, locating relevant literature, Reliability of				-	
•		the research problem, Literature Survey, Research Des				•	•
design.	niiyiiig	the research problem, Enclature Survey, Research De	Sigi	I, IV	iculo	us 01	researen
UNIT	-III	Data Collection				8	hours
Classific	ation of	Data, accepts of method validation, Methods of Data	ı C	olle	ction,	Colle	ction of
		ondary data, sampling, need of sampling, sampling theor					
sampling	g design,	different types of sample designs, ethical considerations	in r	esea	rch.		_
UNIT	-IV	Data Analysis				8	hours
Processi	ng Oper	ations, Data analysis, Types of analysis, Statistical ter	chn	ique	es an	d choo	osing an
		stical technique, Hypothesis Testing, Data processing					
		nce, Chi-Square Test, Analysis of variance (ANOV	A)	and	d cov	varianc	e, Data
Visualiz	ation – N	Monitoring Research Experiments, hands-on with LaTeX.					
UNIT	-	Technical writing and Reporting of Research					hours
		arch report: Dissertation and Thesis, research pap					
		conference presentation etc., Referencing and referencing		-			
Indexing		ation of Journals and Impact factor,	•	ypes			ndexing-
		COPUS/DBLP/Google Scholar/UGC-CARE etc. Significand					
		m, IPR- intellectual property rights and patent law, com					
		ated aspects of intellectual property rights (TRIPS); sch	ola	rly j	publis	shing-	IMRAD
*		gn of research paper, reproducibility and accountability.					
Course	outco	me: Upon completion of the course, the student will be	e al	ole t	:0:		
CO 1	Know	he concept / fundamentals for different types of research					K ₂
CO 2	Annly	-land at a second Deriver to she i and					K ₃
	rppiy	relevant research Design technique					13
CO 3		propriate Data Collection technique					K ₃ K ₃
CO 3 CO 4	Use ap Evalua		ric	test	and	non-	

CO 5 Prepare research report and Publish ethically.	K ₆
Text books	
1. C. R. Kothari, Gaurav Garg, Research Methodology Methods and Technic	ques, New Age
International publishers, Third Edition.	
 Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginner SAGE 2005. 	ers, 2 nd Edition,
3. Deepak Chawla, NeenaSondhi, Research Methodology, Vikas Publication	
Reference Books	
1.Donald Cooper & Pamela Schindler, Business Research Methods, TMGH, 9th ed	dition
2. Creswell, John W, Research design: Qualitative, quantitative, and mixed method sage publications, 2013	s approach

			M. TECH FIRST YEAR		
Co	urs	e Code	AMTME0151	LTP	Credits
Co	ours	e Title	Simulation, Modelling & Analysis Lab	004	2
Co	urse	e objecti	ives:		
1	FLU	UENT, et	e fundamental knowledge on using various analytical to c., for Engineering Simulation.		
2	imp	prove the	rious fields of engineering where these tools can be ef output of a product.	-	
3			nowledge on how these tools are used in Industries by s as using these tools.	olving so	ome real
Pro	e-re	quisites	:		
		should h	ave basic knowledge of Engineering.		
S. 1	No		LIST OF EXPERIMENTS (Total Eight to be perform	med)	
1	l	Study of	f simulation software Like ARENA, MATLAB.		
2	2	Simulati	on of translational and rotational mechanical systems		
3	3	Simulati	on of Queuing systems		
4	1		on of Manufacturing System		
5	5	Generati	ion of Random number		
6	5	Modellin	ng and Analysis of Dynamic Systems		
7	7		on mass spring damper system		
8			on of hydraulic and pneumatic systems.		
9			on of Job shop with material handling and Flexible manuf	acturing	systems
1	0	Simulati	on of Service Operations		
Co	urse	e outcon	1		
CO)1		dent will be able to appreciate the utility of the tools like A T in solving real time problems and day to day problems.	ANSYS o	r K2
CC) 2		hese tools for any engineering and real time applications.		K2
СС) 3	curricul	knowledge on utilizing these tools for a better projectum as well as they will be prepared to handle industry infidence when it matters to use these tools in their employr	problem	

		M. TECH FIRST YEAR							
Cour	se Code	AMTME0152 L T	ГР	Credit					
Cour	se Title	Industry 4.0 LAB 0 0) 4	2					
Cour	se objectivo	es:							
1		will be able to understand and implement the concepts of Ind	lustry 4	4.0					
2		students understand and implement the concepts of Industrial							
3		arize students with concepts of Robotics, AI/ML and AR/VR							
4		udents understand and implement the concepts Additive M	Manufa	acturing	and				
	Reverse Eng	gineering.							
	equisites:								
	ts should hav	ve basic knowledge of Engineering.							
S. No	LIST OF E	EXPERIMENTS (Total Eight to be performed)							
1	Study of a S	Smart Factory setup based on Industry 4.0							
2									
2		ensing and Actuating systems used in Industrial IOT							
3		tion with concept of IoT, Arduino/Raspberry Pi and perform	neces	sary					
	software ins								
4	_	IoT based smart lock system for Motor cycle/Car							
5	Creating a r	model using Augmented Reality (AR/VR Technology)							
6	Study of Na	atural Language Processing including Syntactic, Semantic, D	iscour	se and					
0	Pragmatic F	Processing.							
-	Machine Le	earning Project using Python for Linear Regression analysis of	of fuel						
7	consumptio	onsumption							
8	Operating a	a Robot to perform Pick and place operation using a structure	d prog	gram					
		Simulate the task of Pick the pencil from the magazine and c			&				
9	Square								
10	-	ent of a designed model with given parameters on FDM RP S	vstem						
11		ent of a designed model with given parameters on SLA RP Sy							
11	-			Canning					
12	Technology	Generating point cloud data(3D model) of mechanical components using 3D Scanning							
	Technology	/							
Cour	se outcome	es: After completion of this course students will be able t	to						
COUL		e familiar with the concept of Industry 4.0	.0	L.	K_2				
<u>CO</u>		tand and implement fundamentals of Industrial IOT			K_2 K_2				
		ally implement the concepts of Robotics, AI/ML and	ΔR/		~ 2				
CO	3 Technol	• •	AN/		K_2				
	Learn a	and implement the concepts Additive Manufacturing and	Reve	erse					
CO -	4 Enginee		110,0		K_2				

		M. TECH FIRST YEAR		
Cou	rse Code	AMTME0111	LTP	Credit
Cou	rse Title	Geometric Design & Rapid Prototyping	3 0 0	3
Cou	rse objective:			
		edge on various Geometric Design & Rapid Proto Typi	ng so that	the students
	*	n engineering industry applications.	ing so that	the students
		nding of modelling and design based on component geo	metry	
	ų	nowledge on the design of various components.	Jiiied y	
		ledge and to solve problems associated with design and	ranid prot	otyping and
	*	ts on the latest technology to ensure computer aided ma	A A	• • •
		a good operating condition and at low maintenance cost		g und design
		edge on prototyping systems as well as learn how to per		c procedures
	on a system.			e procedures
	requisites:			
110-	requisites.	Course Contents / Sullabus		
TINIT		Course Contents / Syllabus		4.1
UNI		Geometric Design- Introduction:		4 hours
	1	of CAD/CAM, Introduction to design process and ro	ole of com	puters in the
•	n process.			
		Analytical, Synthetic curves with advantages, Disadvan	•	*
		cometric modelling curves and surfaces, Representation		
	-	tions, Parametric curves and surfaces, Manipulations	of curves	and surfaces,
		fid point line, circle, ellipse algorithms.		
UNI		Solid modelling:		12hours
		entals of solid modelling, Different solid representation		
Boun	dary representat	tion (B-rep), Constructive solid geometry (CSG),	Sweep r	epresentation,
		ng, Perspective, Parallel projection, Hidden line remova	al algorithr	
	T-III	Rapid Prototyping-Introduction:		8hours
		yping, Traditional Prototyping Vs. Rapid Prototyping	· · ·	ssification of
-		Processes: Additive, Subtractive, Formative, Generic R	P process.	
	T-IV	Rapid Prototyping Process		8 hours
Proce	ess Physics, Too	oling, Process Analysis, Material and technological	aspects,	Applications,
limita	ations and com	parison of various rapid manufacturing processes	s. Photop	olymerization
·	• • • •	L), Microstereolithography, Powder Bed Fusion (Se		•
· /	, ·	melting (EBM)), Extrusion-Based RP Systems (Fused		•
		, Sheet Lamination (Laminated Object Manufacturi		
		Beam Deposition (Laser Engineered Net Shaping	(LENS),	Direct Metal
	sition (DMD)			
UNI		CAD/CAM		8 hours
		on, Data interfacing: formats (STL, SLC, CLI, RPI, LE		
	/· · ·	validity checks, repair procedures; Part orientation a		0
		sign, Model Slicing algorithms and contour data o	rganizatio	n, direct and
adant	ive slicing, Tool	path generation.		
uuupt		After completion of this course students will be a	ble to	
	rse outcome:	Ther completion of this course students will be a		
	1 Explain the	e concepts and underlying theory of modelling and the u lifferent engineering applications.		K1,K2
Cou	1 Explain the models in c	e concepts and underlying theory of modelling and the u	sage of	

CO 3	Understand and use techniques for processing of CAD models for rapid	
	prototyping.	
CO 4	Understand and use techniques for processing of CAD Understand and apply	K3, K4,
	fundamentals of rapid prototyping techniques.	K5
CO 5	Use current state-of-the-art CAD/CAM technology in research.	K3,K4

Text Books& Reference Books:

1. Chua C K, Leong K F, Chu S L, Rapid Prototyping: Principles and Applications in Manufacturing, World Scientific.

2. Gibson D W Rosen, Brent Stucker., Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing, Springer.

3. Noorani R, Rapid Prototyping: Principles and Applications in Manufacturing, John Wiley & Sons.

4. Computer Aided Engineering & Design Jim Browne New ATC International

5. The Engineering Database D.N. Chorafas and S.J. Legg Butterworths

6. Principles of CAD J Rooney &P Steadman Longman Higher Education

7. CAD/CAM H P Groover and E W Zimmers Prentice Hall

8. Computer Integrated Design and Manufacture D Bedworth, M Henderson & P Wolfe MacGraw Hill Inc.

	M.TECH FIRST YEAR		
Course Code	AMTME0112	LTP	Credit
Course Title	Advanced Heat and Mass Transfer	3 0 0	3
Course object		1	
	derstand the fundamental concepts of conduction and	its applications	
	derstand the applications of fins and study the design		
3 To un	derstand and demonstrate the principles of radiation a	and heat transfer	phenomenon
	gh radiation		
	ady and identify the phenomenon in convection heat the		
	derstand the basic concepts of mass transfer and its ap	oplications	
Pre-requisites			
	of Engineering Mechanics		
	of Engineering Mathematics aws of Conduction, Convection and Radiation		
Reviews of basic i	Course Contents / Syllabus		
UNIT-I	Conduction		8 hours
	l steady state conduction with variable thermal c	onductivity and	
	ource, Local heat source in non-adiabatic plate, Therr	•	
UNIT-II	Extended Surfaces	<u> </u>	8 hours
	ces-Review, Optimum fin of rectangular profile, s		
	es, Optimum profile, Circumferential fin of recta		
	D steady state conduction, semi-infinite and finite		
	s and in infinite semi-cylinders, spherical shells,	-	-
	ady state conduction, Sudden changes in the surface		
	heres using Groeber's and Heisler charts for plates, o		
immersed in flui		5 1	2
UNIT III	Radiation		8 hours
Review of radia	tion principles, Diffuse surfaces, and the Lambert's	cosine law. Ra	diation through
non-absorbing m	edia, Hottel's method of successive reflections, Geb	hart's unified m	ethod, Poljak's
method. Radiati	on through absorbing media, Logarithmic decre	ment of radia	tion, Apparent
absorptive of sin	pple shaped gas bodies, Net heat exchange between s	urfaces separate	ed by absorbing
medium, Radiati	on of luminous gas flames.		
UNIT-IV	Convection		8 hours
	t transfer in laminar flow, free convection between		
flowthrough circ	ular tubes, fully developed flow, Velocity and therm	nal entry length,	solutions with
	nperature and with constant heat flux, Forced extern		
	ocity and temperature boundary layer equations, Ka		* *
-	Heat transfer in turbulent flow, Eddy heat diffusivit	• •	
	l heat transfer, Prandtl-Taylor, Von Karman and M	lartineli's analo	gies, Turbulent
flow through circ			
UNIT V	Mass Transfer		8 hours
Mass Transfer: I	Definition, Examples, Fick's law of diffusion, Fick's	law as referred	to ideal gases,
-	hermal Equi-molal counter diffusion of ideal gases		•
equation, Isother	mal evaporation of water and its subsequent diffusi	ion into dry air	, Mass transfer
coefficient, Num	erical problems.		
Course outco			1 120 120
	rstand both the physics and the mathematical treatm	ent of the advar	nced K2, K3
topics	s pertaining to the modes of heat transfer		

CO 2	Apply principles of heat transfer to develop mathematical models for uniform	K ₃ , K ₄
	and non-uniform fins	
	Employ mathematical functions and heat conduction charts in tackling two	K_4, K_5
CO 3	dimensional and three-dimensional heat conduction problems.	
CO 4	Analyze free and forced convection problems involving complex geometries	K ₃ , K ₄
0.04	with properboundary conditions.	
CO 5	Apply the concepts of radiation heat transfer for enclosure analysis.	K ₄
005		
CO 6	Understand physical and mathematical aspects of mass transfer.	K_1, K_2
Text Bo	oks	
(1) Princip	oals of Heat Transfer/Frank Kreith/Cengage Learning	
(2)Elemen	nts of Heat Transfer/E. Radha Krishna/CRC Press/2012	
(3)Heat Tr	ransfer/RK Rajput/S.Chand	
Referen	ceBooks	
(1) Introdu	uction to Heat Transfer/SK Som/PHI	
(2) Engine	eering Heat & Mass Transfer/Mahesh Rathore/Lakshmi Publications	
(3)Heat Tr	ransfer / NecatiOzisik / TMH	
(4)Heat Tr	ransfer / Nellis& Klein / Cambridge University Press / 2012	
(2) Engine	eering Heat & Mass Transfer/Mahesh Rathore/Lakshmi Publications	
· · · ·		
(4)Heat Ti	ransfer / Nellis& Klein / Cambridge University Press / 2012	

	M. TECH FIRST YEAR						
Course Code	e AMTME0113 L	ΤI	P	Credit			
Course Title	D LL F C	0 (0	3			
Course obje							
	students understand the concept of renewable and non- renew	wabl	e ene	ergy			
	resources.						
	utilization.						
	To make students understand biogas generation, and hydro-electric generation and its						
	n environment.	<u> </u>		1.			
	students able to identify wind energy as an alternate source of	of en	ergy	and to			
	out how it can be trapped. students aware of the Concept of integration of conventional	land					
	onal energy resources and systems.	i and	non-				
Pre-requisite	e of thermal Engineering.						
Dasic knowledge	Course Contents / Syllabus						
	Introduction		0	1			
UNIT-I		1.1		hours			
	Energy and Development; Energy demand and availabil						
	nd Nonconventional energy; Renewable and Non-renewabl impacts of conventional energy usage; Basic concepts of I						
г · / 1	impacts of conventional energy lisage. Basic concepts of			thund thow			
		neat	anu	iluid ilow			
useful for energ	y systems.	neat					
useful for energy UNIT-II Solar Energy	y systems. Solar Energy Systems Systems: Solar radiations data; Solar energy collection, Stor	rage	8 h and	Durs utilization;			
useful for energy UNIT-II Solar Energy S Electro Chemic storage, solar s	sy systems. Solar Energy Systems	rage rs af	8 ho and t	Durs utilization; ng energy generation;			
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CO 4	Categorize various windmills and their utilization based on their characterization.	K _{3,} K ₄
CO 5	Integrate conventional and non-conventional energy resources and systems for betterment of society.	K ₄
Text	Books	
1.	Energy Efficient Buildings in India Mili Majumdar Tata Energy Research	h Institute
2.	Renewable Energy Systems Simmoes Marcelo Godoy CRC Press	
3.	Renewable Energy Resources John Twidell Taylor and Francis	
Refer	enceBooks	
1.	Renewable Energy Sources and Their Environmental Impact Abbasi & A	Abbasi PHI
2.	Solar Energy - Principles of Thermal Collection and Storage by S P Suk	hatme
3.	Solar Engineering of Thermal Processes by J ADuffie and W A Beckman	1
4.	Principles of Solar Engineering by D Y Goswami and J F Kreider	
5.	Introduction to Sustainable Engineering by R L Rag and Leks	

	M. TECH FIRST YEAR					
Cou	urse Code	AMTME0114	LTP	Credit		
Cou	Course TitleReliability, Maintenance Management & Safety300					
Cou	urse object	ive:				
1		idents able to understand the concept of reliability, its	componen	ts and		
		used to enhance it.	_			
2	2 To make students perceive the knowledge of maintainability, availability, and failure,					
		its effect on quality.				
3		ents able to integrate the concept of maintenance planr the concept of inspection.	ning and re	placement,		
4	-	idents able to use various monitoring techniques, and	its impact	on		
•	reliability.	adents usie to use various momorning teeninques, and	ns impact	011		
5		idents make aware of various safety aspects and hazar	ds associat	ed in plant		
Pre	-requisites	· ·		1		
	1	f Industrial engineering				
		Course Contents / Syllabus				
	IT-I	Reliability Engineering neering: System reliability - series, parallel and mixed		8 hours		
Mai Intro off a Type	oduction, forr among reliab es of failure	Maintainability, Availability & Failure Analysis Availability & Failure Analysis: Maintainabilit nulae, Techniques available to improve maintainabilit ility, maintainability & availability, simple problems es, defects reporting and recording, Defect analys time analysis, Breakdown analysis, TA, FMEA, FME	ty & Ava y & availa , Defect g sis, Failur	bility, trade eneration –		
		Maintenance Planning and Replacement		8 hours		
Maintenance Planning and Replacement: Maintenance planning – Overhaul and repair; Meaning and difference, Optimal overhaul/Repair/Replace maintenance policy for equipment subject to breakdown, Replacement decisions – Optimal interval between preventive replacements of equipment subject to breakdown, group replacement. Maintenance systems, Fixed time maintenance, Condition based maintenance, operate to failure, Opportunity maintenance, design out maintenance, Total productive maintenance, Inspection decision – Optimal inspection frequency, non-destructive inspection, PERT & CPM in maintenance, Concept of terro technology.						
	IT-IV	Condition Monitoring		8 hours		
mon mon	nitoring, lubri nitoring, Con	toring: Techniques-visual monitoring, temperature cant monitoring, Crack monitoring, Thickness monitor dition monitoring of hydraulic system, Machine diag gies, Examples of monitoring and diagnosis, Control	ring, Noise gnostics -	e and sound Objectives,		

diagnosis.		
UNIT V	Safety Aspects	8 hours
Safety Aspects	s: Importance of safety, Factors affecting safety, Safety aspec	ts of site and
plant, Hazards	of commercial chemical reaction and operation, Instrume	ents for safe
operation, Safe	ty education and training, Personnel safety, Disaster planning a	nd measuring
safety effective	ness, Future trends in industrial safety.	
Course outc	ome: After completion of this course students will be ab	le to
CO 1	Perceive the concept of reliability, its components and	K2, K3
	techniques used in it.	
CO 2	Incorporate maintainability, availability, and failure in quality.	K ₃ , K ₄
CO 3	Integrate maintenance planning, replacement, and inspection to quality.	K ₄ , K ₅
CO 4	Make use of various monitoring techniques used.	K ₃ , K ₄
CO 5	Get knowledge on various safety aspects and hazards associated in various industries.	K ₄
Text Books		
1.Concepts in I	Reliability Engineering L.S. Srinath Affiliated East West Press	
	ty and Reliability Handbook Editors: Ireson W.A. and C.F. Coo	mbs McGraw
Hill Inc.	osis and Performance Monitoring L.F. Pau Marcel Dekker	
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ReferenceBo		
	intenance Management S.K. Srivastava S. Chand & Co Ltd.	10.
	of Industrial Maintenance Kelly and M.J. Harris Butterworth an Replacement and Reliability A.K.S. Jardine Pitman Publishing	u C0.
	Maintainability: How to Design for Reliability and Easy Main	tenance D C
	e Hall of India	nenance D.S

		M. TECH FIRSTYEAR	
Course Co	de	AMTME0115 L T P	Credit
Course Tit		Turbo Machines 3 0 0	3
Course obj			
1		y the basics of turbomachinery	
2		y the energy transfer in nozzles and the design of steam turbine b	lades
3		by the fundamentals and design of centrifugal compressors	iuuob
4		y the fundamentals and design of axial flow compressors	
5		y and analyse the design of axial flow gas turbine	
Pre-requis			
		ineering Mechanics	
		gineering Mathematics	
		f thermodynamics	
Reviews of ba	sic laws of	f fluid mechanics	
		Course Contents / Syllabus	
UNIT-I	-	ndamentals of Turbo Machines	8 hours
		lications, Thermodynamic analysis, Isentropic flow. Energy	
		d Stagnation conditions, Continuity equations, Euler's flow thro	ugh variable
	-	Unsteady flow in turbo machines	
UNIT II	Stea	am Nozzles	8 hours
Convergent	and Cor	nvergent-Divergent nozzles, Energy Balance, Effect of back	pressure of
analycic Das	ions of	nozzles. Steam Turbines: Impulse turbines, Compounding, Wo	rk done and
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Velocity trian height, Secon UNIT-III Fundamental relations, Dyn waves. Norm Types, Veloc Slip factor, S UNIT IV Flow Analyst rise, Degree of Cascade Ana Vortex Blade UNIT V Work done. Zweifels rela flow, Free vo Actuator dist Performances	ngle, Effi adary flow Gas thermod namic Pro- nal shock city triang tanitz and Axia is, Work of reaction lysis: Ge s. Axia Velocity tion, Des ortex blad c, Theor s, Matchi Explain t	iciencies, Constant reactions, Blading, Design of blade passages w. Leakage losses, Thermodynamic analysis of steam turbines Dynamics lynamic concepts, isentropic conditions, mach numbers and ar essure, Normal shock relation for perfect gas. Supersonic flow, o k recoveries, Detached shocks, Aerofoil theory. Centrifugal gles and efficiencies, Blade passage design, Diffuser and pressu d Stodolas formula's, Effect of inlet mach-numbers, Pre whirl, Per al Flow Compressors and velocity triangles, Efficiencies, Thermodynamic analysis. St on, Stage Loading, General design, Effect of velocity, Incidence, ometrical and terminology. Blade force, Efficiencies, Losses, Fro al Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, Degreet ign cascade analysis, Soderberg, Hawthrone, Ainley, Correlation e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and cooling ng of compressors and turbines, Off design performance. After completion of this course students will be able to the working principles of turbomachines and apply it to various	s, Angle and 8 hours ea, Velocity blique shock compressor: tre recovery. formance. 8 hours age pressure Performance ee end force, 8 hours of reaction, s, Secondary
Velocity trian height, Secon UNIT-III Fundamental relations, Dyn waves. Norm Types, Veloc Slip factor, S UNIT IV Flow Analyst rise, Degree of Cascade Ana Vortex Blade UNIT V Work done. Zweifels rela flow, Free vo Actuator dise Performances	ngle, Effi dary flow Gas thermod namic Pro- nal shock city triang tanitz and Axia is, Work of reaction lysis: Ge s. Axia Velocity tion, Des ortex blad c, Theor s, Matchi Explain t types of 1	iciencies, Constant reactions, Blading, Design of blade passages w. Leakage losses, Thermodynamic analysis of steam turbines Dynamics lynamic concepts, isentropic conditions, mach numbers and ar essure, Normal shock relation for perfect gas. Supersonic flow, o k recoveries, Detached shocks, Aerofoil theory. Centrifugal gles and efficiencies, Blade passage design, Diffuser and pressu d Stodolas formula's, Effect of inlet mach-numbers, Pre whirl, Per al Flow Compressors and velocity triangles, Efficiencies, Thermodynamic analysis. Ston, Stage Loading, General design, Effect of velocity, Incidence, ometrical and terminology. Blade force, Efficiencies, Losses, Fro al Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, Degree ign cascade analysis, Soderberg, Hawthrone, Ainley, Correlation e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and cooling ng of compressors and turbines, Off design performance. After completion of this course students will be able to the working principles of turbomachines and apply it to various machines	s, Angle and 8 hours ea, Velocity blique shock compressor: the recovery. formance. 8 hours age pressure Performance ee end force, 8 hours of reaction, s, Secondary g of blades, K2
Velocity trian height, Secon UNIT-III Fundamental relations, Dyn waves. Norm Types, Veloc Slip factor, S UNIT IV Flow Analyst rise, Degree of Cascade Ana Vortex Blade UNIT V Work done. Zweifels rela flow, Free vo Actuator dist Performances CO 1	ngle, Effi adary flow Gas thermod namic Pro- nal shock city triang tanitz and Axia is, Work of reaction lysis: Ge is. Axia Velocity tion, Des ortex blad c, Theor s, Matchi Explain t types of 1 Perform	iciencies, Constant reactions, Blading, Design of blade passages w. Leakage losses, Thermodynamic analysis of steam turbines Dynamics lynamic concepts, isentropic conditions, mach numbers and ar essure, Normal shock relation for perfect gas. Supersonic flow, o k recoveries, Detached shocks, Aerofoil theory. Centrifugal gles and efficiencies, Blade passage design, Diffuser and pressu d Stodolas formula's, Effect of inlet mach-numbers, Pre whirl, Per al Flow Compressors and velocity triangles, Efficiencies, Thermodynamic analysis. St on, Stage Loading, General design, Effect of velocity, Incidence, ometrical and terminology. Blade force, Efficiencies, Losses, Fro al Flow Gas Turbines triangle and efficiencies, Thermodynamic flow analysis, Degreet ign cascade analysis, Soderberg, Hawthrone, Ainley, Correlation e, Blade angles for variable degree of reaction. y, Stress in blades, Blade assembling, Material and cooling ng of compressors and turbines, Off design performance. After completion of this course students will be able to the working principles of turbomachines and apply it to various	s, Angle and 8 hours ea, Velocity blique shock compressor: ire recovery. formance. 8 hours age pressure Performance ee end force, 8 hours of reaction, s, Secondary g of blades,

	off-design conditions.	
CO 4	Analyse the design and calculate the design parameters for axial flow compressors.	K4
CO 5	Analyse the cascade design for axial flow gas turbines for various blades	K3, K4
Reference	Books	
(1) Principle	es of Turbo Machines/DG Shepherd / Macmillan	
(2)Fundame	entals of Turbomachinery/William W Perg/John Wiley & Sons	
(3)Element	of Gas Dynamics/Yahya/TMH	
(4) Principle	es of Jet Propulsion and Gas Turbine/NJ Zucrow/John Wiley & Sons/Newyo	ork
TextBook	S	
(1) Turbines	s, Pumps, Compressors/Yahya/TMH	
(2)Practice	on Turbo Machines/ G.Gopal Krishnan &D.Prithviraj/ Sci Tech Publishers,	Chennai
(3)Theory a	nd practice of Steam Turbines/ WJ Kearton/ELBS Pitman/London	
	A	

	M. 7	TECH FIRSTYEAF	2			
Course Code	e AMTME01	16	LTP	Credit		
Course Title	Advanced N	Mechanical Vibrations	300	3		
Course object	ctive:					
	• 1	f vibration and mathematical	• •	le degree		
	·	ibration and damped vibration		1 10 1		
	Understand the analysis of two-degree freedom system under free, damped and forced vibrations and principle and working of different types of vibration absorbers.					
	Ability to carry out exact and numerical analysis of multi degree freedom system					
	ected to different types of vibration.					
	Understand the numerical methods to determine natural frequencies of the beam and					
	free and forced vib					
		brating system under undam	ped and forced v	ibration.		
Pre-requisite Basic knowledge	es: of Industrial enginee	ering				
		rse Contents / Syllabus	5			
UNIT-I	Introduction			8 hours		
		engineering vibration probled and forced vibrations	lems, Review of	single degree		
UNIT-II	Two-degree of F	Freedom Systems		8 hours		
Two-degree of	Freedom Systems	s: Principal modes of vibrat	tion, Spring coup	oled and mass		
		of an undamped close courred damped vibrations, Vib		pled systems,		
UNIT III	Multi-degree Fr	eedom systems		8 hours		
Multi-degree	Freedom systems:	: Eigen-value problem, Clo	ose coupled and	l far coupled		
systems, Ortho	gonality of mode	shapes, Modal analysis f	for free, dampe	d and forced		
vibration system	ns, Approximate me	ethods for fundamental freq	uency- Rayleigh	's, Dunkerely,		
	olzer method, Meth coupled systems.	hod of matrix iteration, Fin	nite element met	hod for close		
UNIT-IV	Continuous syst	ems		8 hours		
	÷	ration of systems governed	by wave equat			
•	s of beams/ bars		•			
Transient Vib	ations: Response t	to an impulsive, step and pul	se input, Shock s	spectrum		
UNIT V	Non-linear Vibr	ations		8 hours		
Non-linear Vi	brations: Non-line	ear systems, Undamped an	d forced vibrati	on with non-		
linear spring for	rces, Self-excited vi	ibrations.				
Course outco	ome: After co	ompletion of this course stu	dents will be ab	le to		
		rent types of vibration degree freedom system und	•	the K2, K3 and		
00.2		concept solve for the mot	tion and the not	K_3, K_4		
Apply	ine mathematical	concept solve for the mot				

	frequency for forced vibration of a two degree of freedom damped or	
	undamped system.	
CO 3	Apply the mathematical analysis of multi degree freedom system subjected to different types of vibration to calculate natural frequency.	K ₄ , K ₅
CO 4	Apply the numerical methods and calculate natural frequencies of the beam and bar under free and forced vibrations.	K _{3,} K ₄
CO 5	Compute the natural frequencies of non-linear vibrating system under undamped and forced vibration.	K ₄
Text I	Books	
Theory	and practice of Mechanical Vibrations J.S. Rao and K. Gupta New Age Inter-	national
	nical Vibrations G.K. Groover Nem Chand & Brothers	
Mechai	nical Vibration Practice V. RamamurtiNarosa Publications	
Refer	enceBooks	
Mechan	nical Vibrations V.P. Singh Dhanpat Rai & sons	
	ok of Mechanical Vibrations R.V. Dukkipati& J. Srinivas Prentice Hall of Ind	lia
	â	

		M. TECH FIRST YEAR	
Co	ourse Code	AMTME0117 L T P	Credit
	ourse Title	Operations Research3 0 0	3
	OURSE OBJECTI		U
1	Ability to unders	tand and analyze managerial problems in industry so that they are able to u als, staffing, and machines) more effectively.	se resources
2	Knowledge of fo	rmulating mathematical models for quantitative analysis of managerial pro	blems in
3	industry. Skills in the use of	of Operations Research approaches and computer tools in solving real prob	lems in
	industry.		
4	Mathematical mo	odels for analysis of real problems in Operations Research.	
Pr	e-requisites		
	•	Course content /syllabus	
Ur	nit-1 Int	troduction 81	Hours
		on and scope of OR; Techniques and tools; Model formulation; genera n of optimization problems; Optimization techniques.	l methods for
			Hours
		Models: Complex and revised simplex algorithms; Duality theorems, sensitive	tivity analysis
As: Inte	signment, transport eger and parametri	ation and transhipment models; Traveling salesman problem as an Assign ic programming; Goal programming. Game Problems: Mini-max criterio zero sum game; Games by simplex dominance rules.	ment problem
			Hours
exp	oonential or Erlang	ems: Classification of queuing situations; Kendall's notation, Poisson service time distribution; Finite and infinite queues; Optimal service rate ndustrial problems.	
Ur	nit-4 Dy	namic Programming 8	Hours
	namic Programmir	ng: Characteristic of dynamic programming problems (DPPs); Bellman with finite number of stages; Use of simplex algorithm for solving DPPs.	's principle of
			Hours
No Op	n-linear Programm	ning: One dimensional minimization method; Unconstrained optimization ues characteristics of a constrained problem; Indirect methods; Search	1
	Course Outcome	es: -After the successful completion of the course, the students will be a	ble to:
(application of OR and frame a LP Problem with solution – graphical.	
			I KZ
1		e Transportation, Assignment and Game Model problems using appropri-	K2 ate K3
1 2	method.	e Transportation, Assignment and Game Model problems using appropri-	ate K3
1 2 3	method. build and solve solve simple pr	e Transportation, Assignment and Game Model problems using appropriate waiting line problems using appropriate method. roblems of replacement and implement practical cases of decision mak	ate K3 K3
$\frac{1}{2}$ $\frac{3}{4}$	method. build and solve solve simple pr under different b analyses the pro	e Transportation, Assignment and Game Model problems using appropriate waiting line problems using appropriate method. roblems of replacement and implement practical cases of decision mak business environments. oblems of unconstrained nonlinear programming. Knows the necessary a	ateK3K3ingK4
1 2 3 4 5	method. build and solve solve simple pr under different l analyses the pro sufficient condit	e Transportation, Assignment and Game Model problems using appropriate waiting line problems using appropriate method. roblems of replacement and implement practical cases of decision mak business environments.	ateK3K3ingK4
1 2 3 4 5	method. build and solve solve simple pr under different l analyses the pro sufficient condit xt Books	e Transportation, Assignment and Game Model problems using appropriate waiting line problems using appropriate method. roblems of replacement and implement practical cases of decision makes business environments. oblems of unconstrained nonlinear programming. Knows the necessary attions for the solution of unconstrained problems.	ateK3K3ingK4
1 2 3 4 5 Te:	method. build and solve solve simple pr under different l analyses the pro sufficient condit xt Books Operations Res	e Transportation, Assignment and Game Model problems using appropriate waiting line problems using appropriate method. roblems of replacement and implement practical cases of decision make business environments. oblems of unconstrained nonlinear programming. Knows the necessary a tions for the solution of unconstrained problems.	K3K3ingK4
$\frac{1}{2}$ $\frac{3}{4}$ $\overline{5}$ $\overline{1}$ $\frac{1}{2}$	method. build and solve solve simple pr under different l analyses the pro sufficient condit xt Books Operations Res	e Transportation, Assignment and Game Model problems using appropriate waiting line problems using appropriate method. roblems of replacement and implement practical cases of decision makes business environments. oblems of unconstrained nonlinear programming. Knows the necessary attions for the solution of unconstrained problems.	K3K3ingK4
$\frac{1}{2}$ $\frac{3}{4}$ $\overline{5}$ $\overline{1}$ $\frac{1}{2}$	method. build and solve solve simple pr under different l analyses the pro sufficient condit xt Books Operations Res Engg. Optimize ference Books	e Transportation, Assignment and Game Model problems using appropriate waiting line problems using appropriate method. roblems of replacement and implement practical cases of decision make business environments. oblems of unconstrained nonlinear programming. Knows the necessary a tions for the solution of unconstrained problems.	K3K3ingK4

		M. TECH FIRST	YEAR				
Cour	se Code	AMTME0118	L	ТР	Credit		
Course Title		Advanced I.C. Engines	3	00	3		
Cour	se objectiv	e:					
1		and classify conventional, modern of	engine technologi	es of I. C	C. Engines.		
2		nd analyze various combustion photon	enomenon and dif	ferent co	omponents		
		f S.I. Engines and C.I. Engines.					
3		competence in performance analys	is, optimization, a	ind conti	rol of IC		
4	engines.	an insight about fuels, alternatives	fuels effect of en	aine out	emissions		
т		nent and emission control methods.		gine out	emissions		
5	To develop	skill and acquire knowledge of mo- mobility solutions.		ologies	and develop		
Pre-r	equisites:	5					
		ndustrial engineering					
		Course Contents / S	yllabus				
UNI	[-I Ir	troduction	•		8 hours		
	uction to diffe l cycles for er	erent types of conventional and mo agines.	dern I.C. Engine,	Valve a	rrangements,		
UNI	Г-II С	ombustion of engines			8 hours		
		SI engines, Knocking parameters	, Combustion cha	mbers co			
					<u> </u>		
		esting and performance nance, Engine cooling & lubrication ntrol.	on, Effects of Suj	percharg	8 hours		
UNI	Γ-IV F	uels			8 hours		
Fuels,	Properties of	f fuels, Rating of fuels, Alternativ gines, pollution control devices, Blu	-	ooling 8	t lubrication,		
UNIT	V M	lodern Technology			8 hours		
	e	Engine, Marine & Aerospace e					
-		hnology, E-Turbocharger, Variabl	-	-	•		
0		and Fuel Cell Technology. Hyb	rid power train c	concepts	and designs		
(series	s, parallel).						
	se outcome	1					
CO	1 Explain technolo		and modern	engine	K2, K3		
CO		and understand the gas exchange	processes and mo	otion of	K ₃ , K ₄		
	charge i and CI e	n the cylinder and its effects on congines.	ombustion proces	ss in SI			
CO		the performance, optimization, and	d control of I.C. e	ngines.	K ₄ , K ₅		
CO	4 Express treatmen	the fuels, alternatives fuels, emiss at.	ions formation ar	nd their	K _{3,} K ₄		

CO 5	Explain and demonstrate modern engine technologies and develop smart future mobility solutions.	K ₄
Text Bo	alva	
Text Do	UKS	
I.C Engine	e Analysis & Practice by E.F Obert.	
I.C Engin	e by Ganesan, Tata McGraw Hill Publishers.	
A Course	in International Combustion Engines, by Mathur& Sharma, DhanpatR	ai& Sons.
Referen	ceBooks	
I.C Engine	e, by R. Yadav, Central Publishing House, Allahabad	
Reciproca	ting and Rotary Compressors, by Chlumsky, SNTI Publications, Czec	hoslovakia
Engineeri	ng Fundamentals of Internal Combustion Engines by W.W. Pulkrabek	, Pearson

		M. TECH FIRST YEAR				
Cou	Course CodeAMTME0201L T PCred					
Cou	rse Title	Digital Manufacturing and Automation (DMA)	3 0 0	3		
Cou	rse objecti	ve:				
1		ding of the Development of CNC Technology and Industr	y 4.0			
2		bout the CNC Programming, G & M Codes, CAM package		ical Design		
3	Smart man	e a detailed interpretation of Tooling for CNC Machines, (ufacturing.	C			
4	Learning a	bout Robotics and Material Handling Systems, Automate	d guided veh	icle systems.		
5		bout the Group Technology and FMS, Understanding and Concurrent engineering.	l Learning ab	out the CIM		
Pre-		Basics of Manufacturing				
	1	Course Contents / Syllabus				
UNI	T-I	Introduction to CNC Machine Tools:		6 hours		
		NC Technology-Principles and classification of CNC ma	chines, Adva			
	1	, Types of control, CNC controllers, Characteristics, Inter	· · ·	0		
DNC	concept. Ind	ustry 4.0				
UNI	T-II	CNC Programming:		8 hours		
Co-o	rdinate Syste	m, Fundamentals of APT programming, Manual part prog	gramming-str	ucture of		
CAM CAM	I packages fo I etc., and use	G & M Codes, developing simple part programmes, Param r CNC machines-IDEAS, Unigraphics, Pro Engineer, CA e of standard controllers-FANUC, Heidenhain and Sinumo gn. 3-D printing.	TIA, ESPIRI	T, Master		
	T-III	Tooling for CNC Machines:		6 hours		
coolin turnir	ng fed tooling	ials, Carbide inserts classification; Qualified, semi qualifi g system, Quick change tooling system, Tooling system fo l holders, Tool assemblies, Tool magazines, ATC mechaning.	or machining	centre and		
UNI	T-IV	Robotics and Material Handling Systems:		8 hours		
Type: Autor manu	s of material mated storage ifacturing.	potic technology, and applications, Robot anatomy, mater handling equipment, Conveyer systems, Automated guide e/retrieval systems, Work-in-process storage, Interfacing	ed vehicle sys	stems,		
UNI		Group Technology and Flexible Manufacturing S	-	12 hours		
Cell I works Com Manu be us	Design, Bene stations, Con puter Integr ifacturing and ed in CIM sy	y-part families, Parts classification and coding, Production fits of Group Technology, Flexible manufacturing system puter control system, Planning for FMS, Applications an ated Manufacturing: Introduction, Evaluation of CIM a d Automation (DMA), CIM hardware and software, Requ stem, Database requirements, Concurrent Engineering-Pr ronment, advance modelling techniques.	s- Introduction d benefits. nd leading to irements of c	on, FMS Digital omputer to		
		1e: Upon completion of the course, the student will be	able to:			
CO 1	l Understar		NC contro	llers, K ₂		

CO 2	Learned about the CNC Programming, G & M Codes, CAM packages, Geometrical	K ₃			
	Design & 3-D printing.				
CO 3	Use detailed interpretation of Tooling for CNC Machines, Cutting tool materials, &	K_3			
	Smart manufacturing.				
CO 4	Know about Robotics and Material Handling Systems, Robot anatomy, Conveyer	K_5			
	systems, Automated guided vehicle systems, Interfacing handling and storage with				
	manufacturing.				
CO 5	Apply detailed interpretation of the GT and FMS, CIM, requirements of computer to	K ₆			
	be used in CIM and DMA, Concurrent engineering.				
Text l	books				
1.0	Computer Numerical Control Machines P. Radhakrishnan New Central Book Agency				
2. 0	CNC Machines M.S. Sehrawat and J.S. Narang Dhanpat Rai and Co.				
3. 0	CNC Programming Handbook Smid Peter Industrial Press Inc.				
Refer	Reference Books				
1. Auto	1. Automation, Production systems and Computer M.P. Groover Prentice Hall of India Integrated				
Manufacturing					
2. Com	2. Computer Integrated Manufacturing Paul Ranky Prentice Hall of India				

		M. TECH FIRST YEAR		
Course C	ode	AMTME0202	LTP	Credit
Course Title		Composite Materials	300	3
Course o	bjective:			
1		and Composite materials and its applications.		
2	To understa	and the various types of composite materials		
3	To know th	e processing techniques of composite materials		
4	Determine	stresses and strains in composites.		
5	Understand	d the mechanical behaviour of laminated composi-	te	
Pre-requirements	isites:The	student should have knowledge of material sci Course Contents / Syllabus	ence and	strength of
UNIT-I	Int	roduction to composites	8 h	ours
		ineering Materials, Concept of composite materi		
Functions of	of a Matrix	, Desired Properties of a Matrix, Polymer Mar	rix (Therr	mosets and
-	· ·	l matrix, Ceramic matrix, Carbon Matrix, Glass		• •
		Role and Selection or reinforcement materials,		
		Aramid fibres, Metal fibres, Alumina fibres, I		
	-	and Silica fibres, Multiphase fibres, Whiskers, Fl Material properties that can be improved by f		
		ering potential.	orning a	composite
UNIT-II		••	Q h	ours
		ssification of composites: on Matrix Material: Organic Matrix compos		
		urbon matrix Composites or Carbon-Carbon Com		
*	· · · · ·	eramic matrix composites (CMC);	posites, 101	
-		on reinforcements:Fibre Reinforced Composit	es, Fibre	Reinforced
		osites, Laminar Composites, Particulate Composi		
Metals, Ad	vantages &	limitations of Composites	_	
UNIT-III	[FA]	BRICATION OF COMPOSITES	8 h	ours
Fabricatio	n method	s: Processing of Composite Materials: Ov	erall cons	siderations
		her Manufacturing Processes like filament w		
		plant method, pultrusion, pre-peg layer, F		
		rix performs, Manufacturing Techniques: To		
materials, I	Release age	nts, Peel plies, release films and fabrics, Bleed	er and brea	ather plies,
bagging file				
		roduction to Nano Composites, Processing of	of nano c	composites,
		of nano composites.	01	
UNIT-IV		perties of Composites		ours
		-Stiffness and Strength: Geometrical aspects -		
		Il continuous fibre, discontinuous fibres, Short thanical Testing: Determination of stiffness	-	
		ites; tension, compression, flexure and shear.	unu su	-115015 01
		ninates	8 h	ours
UNIT-V		IIIIIALEN		I U II I S

Plate Stiffness and Compliance, Assumptions, Strains, Stress Resultants, Plate Stiffness and Compliance, Computation of Stresses, Types of Laminates -, Symmetric Laminates, Antisymmetric Laminate, Balanced Laminate, Quasi-isotropic Laminates, Cross-ply Laminate, Angleply Laminate. Orthotropic Laminate, Laminate Moduli, Hygrothermal Stresses

Course outcome: After completion of this course students will be able to					
CO 1	Understand various matrices and reinforcements used in composites	K ₂ , K ₃			
CO 2	CO 2 Know about polymer matrix composites, metal matrix composites, ceramic Ki matrix composites and its manufacturing and applications				
CO 3	Introduce Fabrication techniques of composites	K3			
CO 4	Determine stresses and strains in composites.	K4			
CO 5	Understand the specifics of mechanical behaviour of layered	K ₄ , K ₅			
	composites compared to isotropicmaterials				
Text bo	ooks				
R. M. Joi	nes, Mechanics of Composite Materials, CRC Press				
M. Mukh	opadhyay, Mechanics of Composite Materials, University Press				
I. S. Dan Press	I. S. Daniel and Ori Ishai, Engineering Mechanics of Composite Material, Oxford University Press				
Reference Books					
K K Chawla, Fibrous Materials, Cambridge University Press.					
Thermal Analysis of Materials by R.F. Speyer, Marcel Decker.					
Engineering Materials: Polymers, Ceramics and Composites A.K Bhargava Prentice Hall India.					

		M. TECH FIRST YEAR				
Cour	Course Code AMTME0251 LTP Cre					
Course Title Automation and Mechatronics Lab		0 0 4	2			
Cour	se objectiv					
1	-	he knowledge on advanced algebraic tools for the c	-			
2	-	he ability to analyze and design the motion for arti	•			
3	To develop a	n ability to use software tools for analysis and des	ign of robot	ic systems.		
		List of Experiments				
1	machine.	out workpiece setting and coordinate setting on V	ertical Millin	ng		
2	Surface ope	ration on Vertical Milling Machine.				
3	Machining	operation using canned cycle on Milling Machine.				
4	Learning al	pout workpiece setting and coordinate setting on T	urning Cent	er.		
5	Performing	Machining operation like Turning, Slotting, Facin	g.			
6		operation using canned cycle and Threading on La	the machine	•		
7		ace Operation on Kuka Kr-10 robot.				
8	-	welding operation using Kuka Kr-10 robot.				
9		controller (Arduino/ Raspberry)				
10	Controller in	nterfacing. ((Arduino/ Raspberry).				
Cour	se outcome	e: After completion of this course students	will be able	to		
CO1	Set machi	ne coordinate and perform machining operations.		K3		
CO2	Program r	obot and perform operations on it.		K4		
CO3	Design a d	controller (Arduino/ Raspberry) and programme it.		K3		
CO4	Interface t	he controller with machine.		K4		

Cou	rse Code	AMTME0252	L T P	Credit
Cour	rse Title	Composite Materials Lab	004	2
Cour	rse objectiv	ve:	·	•
1	To underst	and the metal matrix composite.		
2		and the various types of reinforcement.		
3		ne powder metallurgy techniques.		
4		e stresses and strains in composites.		
5	Understan	d the mechanical behaviour of laminated com	posite	
		List of Experiments		
1	Preparation	n of Metal matrix Composites.		
2	Preparation	n of surface composite by friction stir processi	ng	
3	Study of To	ensile strength and young's modulus of MMCs	5.	
4		model on 3D printer by using glass fiber as a rerial of nylon.	einforcement m	aterial into a
5	Preparation	n of composite by powder metallurgy techniqu	es.	
6	Study of Fl	lexural strength of MMCs.		
7	Study of H	ardness of MMCs.		
8	Impact stre	ength analysis of MMCs		
9	Preparation	n of Al-SiC composites by stir casting method.		
10	-	icrostructure, hardness and density of Al-SiC		
- •	-		*	
Cou	rse outcom	e: After completion of this course stude	ents will be able	e to
(CO1 Pr	repare metal matrix composite.		K2
		an another the fristian stin and assisted		1/2

CO1	Prepare metal matrix composite.	K2
CO2	Demonstrate the friction stir processing.	K3
CO3	Demonstrate the powder metallurgy techniques.	K3
CO4	Determine stresses and strains in composites.	K2

		M. TECH FIRST YEAR		
Cou	rse Code	AMTME0211	LTP	Credit
Cou	rse Title	Advanced Finite Element Analysis	300	3
Coui	rse Objectiv	es: The students should be able to		
1	Understan	d the fundamental concepts and different approaches	used in Finite Elem	ent method.
2	axi-symme	the application of plane stress- strain problem and use optic, heat transfer and fluid flow problems.		
3	plane elem			
4	Understan purpose.	nd and demonstrate the mesh generation used in FEA analy	sis for design and eva	aluation
5	Understan	nd and command the practical application of finite elern ng problems through the use of FEM packages software.	nent method to solv	e realistic
I	UNIT-I	Introduction to Finite Difference Method		8HOUR
1 (Natural co-o Convergence	l formulation of FEM, Variational and Weighted res ordinate system, Element and global stiffness mat and patch test, Higher order elements.	rix, Boundary con	ditions, Erro
1	UNIT-II	Application to plane stress and plane strain proble	ms	8 HOUF
1	Application to plane stress and plane strain problems, Axi-symmetric and 3D bodies, Plate b problems with isotropic and anisotropic materials, Structural stability, Other applications e.g. conduction and fluid flow problems.			
-		th isotropic and anisotropic materials, Structural stat		
Ċ	conduction a	th isotropic and anisotropic materials, Structural stat		
l I	conduction an UNIT-III dealization	th isotropic and anisotropic materials, Structural state nd fluid flow problems.	oility, Other applica	tions e.g., H
c l l r	conduction an UNIT-III dealization naterially no	th isotropic and anisotropic materials, Structural state nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem	oility, Other applica	tions e.g., H
	conduction and UNIT-III dealization dealization naterially no UNIT-IV Organization	th isotropic and anisotropic materials, Structural state nd fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem n-linear problems	bility, Other applica	tions e.g., H 8 HOUE the method 8 HOUE
	conduction an UNIT-III dealization materially no UNIT-IV Organization computer gra	th isotropic and anisotropic materials, Structural state and fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem in-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparat	bility, Other applica	tions e.g., H 8 HOUE the method 8 HOUE
	conduction and UNIT-III idealization of idealization of inaterially no UNIT-IV Organization computer gra UNIT-V FEM an esse	th isotropic and anisotropic materials, Structural state and fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem in-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparat phics, Numerical techniques, 3D problems	ns, Applications of ion and mesh gen ackages, Finite eler	tions e.g., H 8 HOUH the method 8 HOUH eration throu 8 HOUH
	conduction an UNIT-III dealization naterially no UNIT-IV Organization computer gra UNIT-V FEM an esse existing comp Course Out	th isotropic and anisotropic materials, Structural state and fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem on-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparate phics, Numerical techniques, 3D problems FEM an essential component of CAD Intial component of CAD, Use of commercial FEM p plete designs, Comparison with conventional analysis. comes: The students would be able to	bility, Other applica	tions e.g., H 8 HOUH 7 the method 8 HOUH eration throu 8 HOUH nent solution
	conduction and UNIT-III idealization of idealization of idealization of unitr-IV Organization computer graduation UNIT-IV FEM an essee existing comp Course Outo CO1	th isotropic and anisotropic materials, Structural state and fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem on-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparat phics, Numerical techniques, 3D problems FEM an essential component of CAD ntial component of CAD, Use of commercial FEM p plete designs, Comparison with conventional analysis.	bility, Other applica	tions e.g., H 8 HOUH 7 the method 8 HOUH eration throu 8 HOUH nent solution
	conduction an UNIT-III idealization inaterially no UNIT-IV Organization computer grading UNIT-V FEM an essee existing comp Course Out CO1 Appl prob Appl CO2 symr	th isotropic and anisotropic materials, Structural state and fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem on-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparat phics, Numerical techniques, 3D problems FEM an essential component of CAD initial component of CAD, Use of commercial FEM p plete designs, Comparison with conventional analysis. comes: The students would be able to ly the fundamental concepts and approaches to s	bility, Other applica ns, Applications of cion and mesh gen ackages, Finite eler olve realistic engin to global equation	tions e.g., H 8 HOUH the method 8 HOUH eration throu 8 HOUH nent solution heering K ₂ , for axi- K3
	conduction an UNIT-III idealization idealization idealization idealization idealization idealization UNIT-IV Organization computer gra UNIT-V FEM an esse existing comp Course Oute CO1 Appl CO2 symm strain CO3	th isotropic and anisotropic materials, Structural state and fluid flow problems. Idealization of stiffness of stiffness of beam elements in beam-slab problem in-linear problems Organization of the Finite Element programmer of the Finite Element programmer, Data preparate phics, Numerical techniques, 3D problems FEM an essential component of CAD intial component of CAD, Use of commercial FEM p plete designs, Comparison with conventional analysis. comes: The students would be able to ly the fundamental concepts and approaches to s elems. y the fundamental concepts of boundary conditions metric, heat transfer and fluid flow problems and solve the	bility, Other applica ns, Applications of ion and mesh gen eackages, Finite eler olve realistic engine to global equation ose displacements, str	tions e.g., H 8 HOUH The method 8 HOUH eration throu 8 HOUH nent solution heering K ₂ , for axi- ress and

	Develop proficiency in the application of the finite element method (modelling, analysis,	K ₄ , K ₅
CO5	and interpretation of results) to realistic engineering problems through the use of a major	
	commercial general-purpose finite element code.	

Tex	t Books
1	The Finite Element Method O.C. Zienkiewicz and R.L. Taylor McGraw Hill
2	An Introduction to Finite Element Method J. N. Reddy McGraw Hill
3	Finite Element Procedure in Engineering Analysis K.J. Bathe McGraw Hill
4	Finite Element Analysis C.S. Krishnamoorthy Tata McGraw Hill
Refe	erences Books:
1	Concepts and Application of Finite Element Analysis R.D. Cook, D.S. Malcus and M.E. Plesha John Wiley
2	Introduction to Finite Elements in Engineering T.R Chandragupta and A.D. Belegundu Prentice Hall India
3	Finite Element and Approximation O.C. Zenkiewicy& Morgan

		M. TECH FIRST YEAR		
Course Cod	le	AMTME0212	LTP	Credit
Course Title	e	Modern Manufacturing Technology	300	3
Course obje	ective:	g_	• • •	
		stand the non-traditional manufacturing process		
		stand the concept of ultrasonic machining.		
		be the electrical discharge machining		
		be the electrochemical machining and hybrid machini	ing	
		stand the unconventional welding and forming.	0	
Pre-requi		<u>_</u>		
1		Course Contents / Syllabus		
UNIT-I		Introduction:		7 hours
Need of No	on-Tradi	tional Machining Processes, ClassificationBased o	n Energy,	Mechanism
		ansfer media and process, Process selection Based of		
shapes to be	machine	ed, process capability and economics, Overview of all	processes	
UNIT-II		Ultrasonic Machining		8 hours
Ultrasonic	Machin	ing: Principle- Transducer types, Concentrate	ors, Abra	asive Slurry
	meters, '	Tool Feed Mechanism, Advantages and Limitations,	Applicati	ons. Abrasive
Jet Machinii	ng: Proc	ess- Principle, Process Variables - Material Remova	ıl Rate, Ac	lvantages and
Limitations,	Applica	tions. Water Jet Machining: Principle, Process Var	riables, Ac	lvantages and
Limitations,	Practica	lApplications, Abrasive water jet machining process.		
UNIT-III		Electrical Discharge Machining		8hours
Electrical Di	ischarge	Machining: Mechanism of metal removal, Dielectric	Fluid, Flus	hingmethods
Electrode M	laterials,	Spark Erosion Generators, Electrode Feed System,	Material R	emoval Rate
ProcessPara	meters, '	Tool Electrode Design, Tool wear Characteristics of	Spark Ero	ded Surfaces-
Advantages	and Lim	itations, Practical Applications. Electrical Discharge	Wire Cut	and Grinding
Principle, W	Vire Fee	d System, Advantages and Limitations - Practical	l applicati	ons, Electron
Beam Mach	ining, pl	asma arc machining, laser beam machining		
UNIT-IV		Chemical, Electrochemical and Hybrid Machin	ing	8 hours
		Process		
		Process: material removal mechanism, process parar		
		achining process: Material Removal Mechanism	n, process	parameters,
applications,				
		process: principle of unconventional hybrid	machin	ing process,
	ical grin	ding, electrochemical spark machining.		0.1
UNIT-V		Advanced Welding and forming Techniques		8 hours
		xplosive welding, Diffusion bonding, High freque		tion welding
Ultrasonic welding, Electron beam welding, Plasma arc welding, Laser welding.				
Principle of high energy rate forming, explosive forming, electrohydraulic forming,				
electromagn	ette torn	ning, incremental forming processes.		
Course ou	itcome	After completion of this course students will	be able to	
CO 1	underst	and the concepts of modern manufacturing technolog	у	K1,K2
CO 2	Apply	the concept of mechanical processes such as u	ıltrasonic	K3, K4

Books:		
CO 5	Apply the concept of unconventional metal forming process.	K3,K4
CO 4	Understand the concept of unconventional welding processes.	K3, K4, K5
CO 3	Understand the concept of electrochemical machining process.	
	machining, AJM,WJM	

1. P.C Pandey And H.S. Shan, "Modern Machining Process", Tata Mc Graw – Hill Publishing Company Limited, New Delhi, 2007.

2. V.K. Jain, "Advanced Machining Process", Allied Publishers Pvt Limited 200.

3. Amitabha Bhattacharyya, "New Technology", The Institution of Engineers, India

4. HMT Bangalore, "Production Technology", Tata Mc Graw–Hill Publishing Company Limited, New Delhi, 2006.

5. Hassan El – Hofy "Advanced machining Processes" MC Graw-Hill, 2005.

		M. TECH FIRST YEAR		
Cours	se Code	AMTME0213	LTP	Credit
Cours	se Title	Advanced Welding Technology	300	3
	se objectiv			
1		nowledge on various advanced welding processes so	that the st	udents can
		in engineering industry applications.		
2		erstanding of heat flow and temperature distribution	on weld c	omponents
		eld geometry		-
3		the knowledge on the design of welded joints and the	quality c	ontrol of
	weldments.			
4		knowledge and to solve problems associated with fail		*
		the latest technology to ensure welded structure are n	naintained	in good
5		ondition and at low maintenance cost.	. 1. avr. 6 a	aufama
3	*	nowledge on robotic welding systems as well as learn lures on a system.	now to p	eriorm
Dro n	equisites:			
116-10	equisites.	Course Contents / Sullabus		
TINIT		Course Contents / Syllabus		4 1
UNIT		ding Metallurgy:	0 1 1	4 hours
		ed with other fabrication processes, Classification of		
		e and its characteristics; Effects of alloying eleme		
	•	els, stainless steel, cast iron, and aluminum and tit		•
testing	standards,	Hydrogen embrittlement, Lamellar tearing, residu	al stress	es and its
measur	rement, heat	transfer and solidification, Analysis of stresses in w	elded stru	ctures. Pre
		eat treatments, Metallurgical aspects of joining, Con		
		g of materials		solucing,
UNIT	-	d Design & Quality Control:		12 hours
		ed with other fabrication processes, Classification of		
		e and its characteristics; Effects of alloying eleme		
	•	els, stainless steel, cast iron, and aluminium and tit		•
		Hydrogen embrittlement, Lamellar tearing, residu		
measur	rement, heat	transfer and solidification, Analysis of stresses in we	elded stru	ctures, Pre
		eat treatments, Metallurgical aspects of joining, Con		
		g of materials.		U,
UNIT	-	lern Trends in Welding:		8 hours
Friction		xplosive welding, Diffusion bonding, High frequence	v inductio	
	0,	Electron beam welding, Plasma arc welding, Laser v		6)
UNIT		air Welding and Reclamation:		8 hours
		ts of repair, aspects to be considered for repai	ir weldin	
		velding procedures for components made of steel ca		
half bead, temper bead techniques, usage of Ni base filler metals. Types of wear, wear				
resistant materials, selection of materials for various wear applications; reclamation				
surfacing techniques, selection of welding process for reclamation				
UNIT		tics in Welding:		8 hours
		applications in welding, Programming of welding ro	obots. tole	
		bt welding, New generation of welding robots, Self-a		
		bots for car body welding, Microelectronic weld		
	,	J O'	0	8,

Efficiency of robotics in welding.

CO 1	Identify and understand the concepts of welding	K1,K2
CO 2	Analyze peak temperatures, HAZ stresses and to prevent distortions	K3, K4
CO 3	Analyze and predict the life of weld joints subjected to fatigue and evaluate the effect of stress concentration on fatigue life of such joints.	K4
CO 4	Selection of repair welding and apply techno-economics for practical problems.	K3, K4, K5
CO 5	Use appropriate safety precautions while programming and operating the robot system	K3,K4
Books:		
1 Advanged Welding Processon Nikedage & Shangky MIP Publications		

1. Advanced Welding Processes Nikodaco&Shansky MIR Publications

2. Welding Technology and Design VM Radhakrishnan New Age International

3. Source Book of Innovative welding Processes M.M. SchwarizAmerican Society of Metals (Ohio)

4. Advanced Welding Systems, Vol. I, II, III J. CornuJaico Publishers

5. Manufacturing Technology (Foundry, Forming and Welding) P.N. Rao Tata McGraw Hill

6. Welding principles and practices by Edward R. Bohnart, Mc. Graw Hill Education, 2014.

7. Welding and Welding technology, Richard L little, Mc. Graw Hill Education

8. Welding processes and Technology – Dr.ParmarRS

9. Welding processes and Technology – O.P Khanna 10. Foundry, Forming and Welding, P.N.Rao 2nd Edition TMH
| | | M. TECH FIRST YEAR | | |
|--|--|--|-------------|--|
| Cour | se Code | AMTME0214 | LTP | Credit |
| Cour | se Title | Computational Fluid Dynamics (CFD) | 3 0 0 | 3 |
| Cours | e objective: | | | |
| This c | ourse enable | s students to | | |
| 1. | | rovide brief introduction of Computational Fluid Dyr
rsis of fluid mechanics and heat transfer related problem | | ned with the |
| | anary | Course Contents / Syllabus | 15. | |
| UNIT | -I INT | RODUCTION | | 8 hours |
| Introd | uction. Cons | servation equation, Mass Momentum and Energy | equations. | |
| | | on and general description. | I , | |
| UNIT | -II Bou | ndary and initial conditions | | 8 hours |
| Clarifi | ication into | various types of equation, Parabolic, Elliptic, | Boundary | and initial |
| | | ew of numerical methods | | |
| UNIT | -III Fini | te difference methods | | 8 hours |
| Interfa
UNIT | ICE and free | nt of boundary conditions; Boundary layer treatm
surface treatment, Accuracy of F.D. method.
tion of finite difference equations
difference equations; Iterative methods; Matrix in | | 8 hours |
| | | splitting, Fast Fourier Transform applications | | |
| UNIT | -V Phas | se change problems | | 8 hours |
| function | ons, One- a | alama Davilaiah Dita Caladrin and Lagat anyong | methods; In | o nours |
| | | olems, Rayleigh-Ritz, Galerkin and Least square
and two-dimensional elements, Applications. Ph
less for moving boundary; Variable time step metho | | nterpolation
problems; |
| | Course Ou | and two-dimensional elements, Applications. Phases for moving boundary; Variable time step metho | | nterpolation
problems; |
| CO1 | | and two-dimensional elements, Applications. Phases for moving boundary; Variable time step metho | | nterpolation
problems |
| CO1
CO2 | Understand | and two-dimensional elements, Applications. Phases for moving boundary; Variable time step methon atcome: | | nterpolation
problems;
method. |
| CO2 | Understand
Apply boun | and two-dimensional elements, Applications. Phases for moving boundary; Variable time step methon itcome:
the various governing equations related to CFD. | d, Enthalpy | nterpolation
problems
method. |
| CO2
CO3 | Understand
Apply boun
Apply Finit | and two-dimensional elements, Applications. Phases for moving boundary; Variable time step methon the various governing equations related to CFD. dary condition & initial conditions. | d, Enthalpy | hterpolation
problems:
method.
K2
K3 |
| CO1
CO2
CO3
CO4
CO5 | Understand
Apply boun
Apply Finit
Evaluate the | Ind two-dimensional elements, Applications. Phases for moving boundary; Variable time step methon itcome:
the various governing equations related to CFD.
dary condition & initial conditions.
e Difference and Finite Volume methods in CFD model | d, Enthalpy | kerpolation
problems;
method.
K2
K3
K3 |
| CO2
CO3
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CO5 | Understand
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of Authors | and two-dimensional elements, Applications. Phases for moving boundary; Variable time step methon
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e Difference and Finite Volume methods in CFD model
e performance of fluid dynamics model.
the various governing equations related to CFD.
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problems;
method.
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		M. TECH FIRST YEAR		
Course	e Code	AMTME0215	L T P	Credit
Course		Advanced Mechanics of Solids	300	3
	objective:			
	3	students to		
2.	Solve adv	vanced solid mechanics problems using classic	al methods	
3.		nd behaviour of machine and structure under v		conditions
4.	Understa	nd hardening rules and different elastic consta	int relations for	materials like
	isotropic,	anisotropic, hyper elastic and viscoelastic		
5.	Understa	nd boundary value problem which is applicabl	e not only in so	lid mechanics
		n heat transfer, fluid mechanics and acoustic d		
6.		nd principle of virtual work and time depender		
7.		rse also aims at creation of an environmen		
		ed to solve problems on advanced solid me	echanics and in	n this way to
	improve	their solving skills.		
		Course Contents / Syllabus		
UNIT-I		DUCTION		8 hours
		minaries: Scalars, vectors and matrix varial		
		sian tensors and their algebra, coordinate tr		
		order tensors, elements of tensor calculus		
		s' and Green's), principal value theorem, e	igenvalues and	eigenvectors,
		rder tensor. nation: Types of forces (point, surface and be	1-1 4	
Kinetics	of Deform	nation. Types of forces (point surface and po		astan state of
	t a point			
stress a		Cauchy's relation and its proof, conserva-	ation of linear	and angular
stress at moment	um, stress	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress	ation of linear tensor, stress tr	and angular cansformation,
stress at moment principal	um, stress l stresses	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress t and the associated planes, 3D Mohr's circ	ation of linear tensor, stress tr ele representation	and angular ransformation, on, planes of
stress a moment principa maximu	um, stress l stresses m shear, o	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress t and the associated planes, 3D Mohr's circ ctahedral planes, hydrostatic and deviatoric s	ation of linear tensor, stress tr ele representation	and angular ransformation, on, planes of
stress a moment principa maximu Kirchoff	um, stress l stresses m shear, of f stress tens	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress t and the associated planes, 3D Mohr's circ ctahedral planes, hydrostatic and deviatoric s ors and their properties.	ation of linear tensor, stress tr ele representation tress, first and	and angular ransformation, on, planes of second Piola-
stress a moment principal maximu Kirchoff	um, stress 1 stresses m shear, of f stress tens I Kiner	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress t and the associated planes, 3D Mohr's circ ctahedral planes, hydrostatic and deviatoric s ors and their properties. matics of Deformation	ation of linear tensor, stress tr ele representation tress, first and	and angular ransformation, on, planes of second Piola- 8 hours
stress at moment principat maximut Kirchoff UNIT-II Kinemat	um, stress 1 stresses m shear, of f stress tens I Kiner tics of De	Cauchy's relation and its proof, conservative equilibrium equations, symmetry of stress that and the associated planes, 3D Mohr's circle catahedral planes, hydrostatic and deviatoric stores ors and their properties. matics of Deformation formation: Material and spatial co-ordinated	ation of linear tensor, stress th ele representation tress, first and s, Eulerian an	and angular ransformation, on, planes of second Piola- 8 hours d Lagrangian
stress at moment principal maximut Kirchoff UNIT-II Kinemat descripti	um, stress 1 stresses m shear, of f stress tens I Kiner tics of De- tion of motion	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress that and the associated planes, 3D Mohr's circle etahedral planes, hydrostatic and deviatoric stors and their properties. matics of Deformation formation: Material and spatial co-ordinate on; deformation and displacement gradients, or	ation of linear tensor, stress tr ele representation tress, first and s, Eulerian an Green-Lagrange	and angular ransformation, on, planes of second Piola- 8 hours d Lagrangian e and Almansi
stress a moment principal maximut Kirchoff UNIT-II Kinemat descripti strain ter	um, stress 1 stresses m shear, of f stress tens I Kiner tics of De tion of motion nsor; Cauch	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress that and the associated planes, 3D Mohr's circle etahedral planes, hydrostatic and deviatoric stors ors and their properties. matics of Deformation formation: Material and spatial co-ordinate on; deformation and displacement gradients, on by's small strain tensor and the rotation tensor.	ation of linear tensor, stress tr ele representation tress, first and s, Eulerian an Green-Lagrange , geometrical in	and angular ransformation, on, planes of second Piola- 8 hours d Lagrangian e and Almansi terpretation of
stress at moment principal maximu Kirchoff UNIT-I Kinemat descripti strain ter strain co	um, stress 1 stresses m shear, of f stress tens I Kinen tics of De tion of motion nsor; Cauch omponents	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress that and the associated planes, 3D Mohr's circle etahedral planes, hydrostatic and deviatoric stors and their properties. matics of Deformation formation: Material and spatial co-ordinate on; deformation and displacement gradients, or	ation of linear tensor, stress the ele representation tress, first and s, Eulerian an Green-Lagrange , geometrical in directions, stra	and angular ransformation, on, planes of second Piola- 8 hours d Lagrangian e and Almansi terpretation of un invariants,
stress at moment principal maximu Kirchoff UNIT-I Kinemat descripti strain ter strain co	um, stress l stresses m shear, of f stress tens I Kiner tics of De ion of motionsor; Cauch omponents ral strain, m	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress that and the associated planes, 3D Mohr's circle cathedral planes, hydrostatic and deviatoric stors ors and their properties. matics of Deformation formation: Material and spatial co-ordinate on; deformation and displacement gradients, on and sign convention, principal strains and	ation of linear tensor, stress the ele representation tress, first and s, Eulerian an Green-Lagrange , geometrical in directions, stra compatibility en	and angular ransformation, on, planes of second Piola- 8 hours d Lagrangian e and Almansi terpretation of ain invariants, quations.
stress at moment principal maximut Kirchoff UNIT-II Kinemat descripti strain ter strain co octahedr UNIT-II	um, stress1stresses1stressesmshear, orf stresstensIKinerticsofticsofofmotionnsor;Cauchomponentsral strain, mIICons	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress that and the associated planes, 3D Mohr's circle etahedral planes, hydrostatic and deviatoric stores ors and their properties. matics of Deformation formation: Material and spatial co-ordinate on; deformation and displacement gradients, of hy's small strain tensor and the rotation tensor, and sign convention, principal strains and aximum shear strain, volumetric strain, strain titutive Modelling	ation of linear tensor, stress tr ele representation tress, first and s, Eulerian an Green-Lagrange , geometrical in directions, stra compatibility ec	and angular ransformation, on, planes of second Piola- 8 hours d Lagrangian e and Almansi terpretation of in invariants, quations. 8 hours
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stress at moment principal maximut Kirchoff UNIT-II Kinemat descripti strain ter strain co octahedr UNIT-II Constitu Generali anisotrop relations UNIT-I Boundar Navier e stress an UNIT-V Variation	um, stress l stresses a m shear, ou f stress tens I Kiner tics of De tion of motion nsor; Cauch omponents ral strain, m I Cons tive Model tized Hooka pic, hyper s for elasto- V Boun ry Value P equations, E tid plane stra V Varia nal Princip al, Euler-I	Cauchy's relation and its proof, conserva equilibrium equations, symmetry of stress to and the associated planes, 3D Mohr's circle etahedral planes, hydrostatic and deviatoric stores ors and their properties. matics of Deformation formation: Material and spatial co-ordinate on; deformation and displacement gradients, on and sign convention, principal strains and aximum shear strain, volumetric strain, strain titutive Modelling ling: Thermodynamic principles, first and sec- e's law for isotropic materials, elastic co- elastic and viscoelastic material models, s plastic materials, flow and hardening rules. dary Value Problems Problems in Linear Elasticity: Field equation Beltrami-Michell stress compatibility condition in) and solution strategies. tional Principles in Solid Mechanics: les in Solid Mechanics: Elements of variation	ation of linear tensor, stress the ele representation tress, first and s, Eulerian an Green-Lagrange , geometrical in directions, stra compatibility ex- cond law of the onstants and the train hardening has and boundar ns, 2D approxim- onal calculus, e es of boundar	and angular ransformation, on, planes of second Piola- 8 hours d Lagrangian e and Almansi terpretation of in invariants, quations. 8 hours rmodynamics, neir relations, g, constitutive 8 hours ry conditions, nations (plane 8 hours xtremum of a y conditions,

	Course Outcome:				
CO	CO1 Students who successfully complete this course obtains advanced information on Advanced Mechanics of Solids and will be able to		K2		
CO	CO2 Solve mechanics problem using matrix, vector and use element of tensor calculus.				
CO.	CO3 Learn about the elastic and plastic behaviour of material and K3 evaluate stress invariants, principal stresses and their directions				
CO4	4	Determine strain invariants, principal strains and their directions	K3		
CO	CO5 Understand the theory of elasticity including strain/displacement, Hooke's law for isotropic material, elastic constants and their relationships				
Nar	ne of Au	thors/ Books / Publisher			
1		I.H., "Elasticity Theory Applications and Numerics", Elsevier Acaden	nic Press.		
2	Boresi, A.P., Sidebottom, O. M., "Advanced Mechanics of Materials", 5th Ed., John Wiley and Sons				
3	Singh, A	A.K., "Mechanics of Solids", PHI Learning Private Limited			
4	Timoshe	enko, S.P., and Goodier, J.M., "Theory of Elasticity", 3rd Ed., McGra	w Hill		
5	Srinath, L.S., "Advanced Mechanics of Solids", Tata McGraw Hill Education Private Limited				
6	Fung, Y	.C., "Foundations of Solid Mechanics", Prentice Hall Inc.			

M. TECH FIRST YEAR				
Course Code	AMTME0216	LTP	Credit	
Course Title	Optimization Techniques	300	3	
Course Objectiv	es: The students should be able to		·	
1	To introduce various optimization techniques i.e. classical, linea1programming, transportation problem, simplex algorithm, dynamiprogramming			
2	Constrained and unconstrained optimization tech optimizing an electrical and electronic engineering c real world situations.	-	-	
3	To explain the concept of Dynamic programming project implementation.	g and its ap	plications to	
4	To introduce various Advanced optimization tec geometric programming, genetic algorithm and simula	-	-	

UNIT – I Introduction

8 HOURS

Introduction and Classical Optimization Techniques: Statement of an Optimization problem, design vector, design constraints, constraint surface, objective function, objective function surfaces, classification of Optimization problems. Classical Optimization Techniques: Single variable Optimization, multi variable Optimization without constraints, necessary and sufficient conditions for minimum/maximum, multivariable Optimization with equality constraints. Solution by method of Lagrange multipliers, Multivariable Optimization with inequality constraints, Kuhn – Tucker conditions.

UNIT-II Linear Programming

8 HOURS

Linear Programming: Standard form of a linear programming problem – geometry of linear programming problems – definitions and theorems – solution of a system of linear simultaneous equations – pivotal reduction of a general system of equations – motivation to the simplex method – simplex algorithm. Transportation Problem: Finding initial basic feasible solution by north – west corner rule, least cost method and Vogel's approximation method – testing for optimality of balanced transportation problems.

UNIT-III Unconstrained Nonlinear Programming

8 HOURS

Unconstrained Nonlinear Programming: One dimensional minimization. methods, Classification, Fibonacci method and Quadratic interpolation method Unconstrained Optimization Techniques: Univariant method, Powell's method and steepest descent method.

UNIT-IV	Dynamic programming	8 HOURS

Dynamic programming: Evolutionary algorithms: Genetic Algorithm, concepts of multiobjective optimization, Markov Process, Queuing Models

UNIT-V	Advanced optimization techniques	8 HOURS
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Advanced optimization techniques: integer and geometric programming, genetic algorithm, simulating annealing, optimization software's.

Cour	rse Outcomes: The students would be able to				
CO		K2			
CO2	understand optimization of mechanical systems and formulate the optimization problems.				
COS	CO3 apply classical optimization techniques, linear programming, simplex algorithm, transportation problem				
CO	apply unconstrained optimization and constrained non-linear programming and dynamic programming	K4			
CO	Understand the advanced optimization techniques.	K3			
1 2 REF	 Singiresu S. Rao, Engineering Optimization: Theory and Practice by John Wiley a 4th edition, 2009. H. S. Kasene& K. D. Kumar, Introductory Operations Research, Springer (India), I 2004 ERENCE BOOKS: 				
4	George Bernard Dantzig, Mukund Narain Thapa, "Linear programming", Springer operations research 3rd edition, 2003.	series in			
5	H.A. Taha, "Operations Research: An Introduction", 8th Edition, Pearson/Prent 2007.	tice Hall,			
6	Kalyanmoy Deb, "Optimization for Engineering Design – Algorithms and Examples", PHI Learning Pvt. Ltd, New Delhi, 2005.				

		M. TECH FIRST YEAR					
Cour	se Code	AMTME0217	L T P	Credit			
Cour	se Title	Artificial Intelligence and Machine Learning (AIML)	300	3			
Cour	Course objectives:						
1							
2							
3	Help stud	lents to learn the application of AI / Machine learning					
	equisite			<u> </u>			
Studen	ts should	have basic knowledge computers, general engineering an	d mathem	atics.			
		Course Contents / Syllabus					
UNIT]-I	FUNDAMENTALS OF AI	8	hours			
		to AI, History of AI, Intelligent Systems, Types of Intelli	igence				
· ·	A	and Research Areas of AI					
Ŭ		Environments SEARCH TECHNIQUES AND KNOWLEDGE					
UNIT		REPRESENTATION		hours			
		Search, Types of search -BFS, DFS, Bidirectional Search	, Heurisitc	search -			
		g, Beam Search Best First, A* search algorithm.	antation	lagia			
	•	Representation, Relational knowledge, Knowledge repres twork, Frame based knowledge.	entation as	logic,			
UNIT		SCOPE OF AI	8	hours			
- Na	tural Lang	uage Processing					
	pert Syste						
	zzy Logic	•					
	ural Netw						
UNIT		INTRODUCTION TO MACHINE LEARNING	10) hours			
		to Machine learning systems.					
	·	earning, Unsupervised Learning and Deductive Learning ural Networks	3.				
UNIT		Applications	8	hours			
			0	liouis			
	e	ce recognition,					
	ject recog						
		gnition besides Computer Vision, and Robotics					
- Au	tomation	and Kobolics					
Cour	Course outcome: After completion of this course students will be able to						
CO		n the fundamentals of AI with engineering perspectives.		K ₂			
CO		rstand concept of knowledge representation and predi- ransform the real-life information in different representat	•	K ₂			
CO 3	3 Unde	rstand state space and its searching strategies.		K ₂			
CO 4	CO 4 Understand machine learning concepts and range of problems that can k ₂ k ₂						

CO 5	Understand the concepts of face, object, speech recognition and automation & robotics.	K ₂
Text &F	Reference books	
1. Elaine	Rich, K. Knight, "Artificial Intelligence", 2/E, TMH, 1991.	
2. Andre	w C., Staugaard Jr., Robotics and AI: "An Introduction to Applied Machine	;
Intelli	gence", Prentice Hall ,1987.	
3. S. Rus	sell and P. Norvig, "Artificial Intelligence: A Modern Approach", 2/E, Pren	ntice
Hall, 2	2003.	
4. K. Boy	yer, L. Stark, H. Bunke, "Applications of AI, Machine Vision and Robotics'	' World
Scient	ific Pub Co. , 1995.	
5. I. Brat	ko, "Prolog Programming for Artificial Intelligence", 3/E, Addison-Wesley	, 2001.
6. C. M.	Bishop, "Pattern Recognition and Machine Learning", Springer, 2003.	

		M. TECH FIRST YEAR		
Cou	irse Code	AMTME0218	L T P	Credit
	arse Title	Management Information System	300	3
	irse objecti			1
1	To make s	tudents Identify and understand the role of	MIS in	business and
	management			
2	· ·	roblems pertaining to conceptual information and	l detailing i	nformation of
2	a system des	•	4	
3	economics.	udents Evaluate and differentiate various inform	hation syste	ems and their
4	Students wi	Il be able to understand the strategic and proje	ect planning	g and role of
	Information	system in decision making.	-	-
5		udents integrate information system to ERP, ar	nd other E	nterprise-wide
	•	g-with ethics.		
Pre	-requisites:	The student should have knowledge of Manufactu	ring scienc	e
		Course Contents / Syllabus		1
		roduction toFlexible manufacturing syst		8 hours
		aning and definition of management information		
		MIS in facing increasing complexity in business and		
		mation systems design; Problem Definition; se		
	•••	n constraints; Determining information needs;		0
		ngalternative conceptual designs; Documenting th	e conceptua	
		niling information systems design		8 hours
		ation systems design; Informing and involving		
	-	IS; Identifying dominant and tradeoff criteria; S	Subsystem	definition and
sour		I /· · · · /· /·		
		luation of information systems		8 hours
syste		formation systems; Basic information system n and operations information systems; Marketi onsystem etc		
		rmation systems for decision making		8 hours
		ems for decision making; Programmed and nor	1-nrooramn	red decisions:
		ision support systems, Strategic and project plann		
UN	IT-V Ent	erprise-wide information systems		8 hours
		information systems; Integration with EF	RP system	
		gration with external organizations; Virtu		ations; data
0	· · ·	ta mining; OLAP(Online Analytical Processi		ms, Business
		ethics, crime, and security.	0)	,
Cou	irse outcom	e: After completion of this course students	s will be ab	le to
CC	1			V V
	0.1 Define N	IIS and its involvement in Business and Managem	ient	K_2, K_3
CC	0.2 Discuss	and define the problems related to design of information system.		
	D 2 Discuss detailing D 3 Evaluate	and define the problems related to design of	conceptual	and K3
CC	 D 2 Discuss detailing D 3 Evaluate economi 	and define the problems related to design of information system. and differentiate various information system a	conceptual long with	and K3

Text books& Reference Books

- 1. Management Information Systems O' Brien, J Tata McGraw Hill
- 2. Management Information Systems W.S. Jawedker Tata McGraw Hill
- 3. Management Information Systems S Sadagopan Prentice Hall of India
- 4. An Information System for Modern Management R.G. Mudrick Pearson
- 5. Management Information Systems M. Jaiswal Oxford University Press

		M. TECH FIRST YEAR		
Course	Code	AMTME0219	LTP	Credit
Course		Flexible Manufacturing System	300	3
	objectiv	/e:		
1		vill learn the flexible manufacturing system.		
2	Student v	vill learn the data-based management system.		
3		vill understand the group technology.		
4		vill learn the coordinate measuring machine tool.		
5		vill understand the material requirement planning system	•	
Pre_rea	misites	Γhe student should have knowledge of Manufacturin	a science	
110-109		Course Contents / Syllabus	ig science	
UNIT-I	Int	roduction to Flexible manufacturing system	m	8 hours
Introduc		roduction to manufacturing system, different ty		anufacturing
technolog handling system:	gy, FMS system, F Computer	stem: Components of an FMS, types of system, work stations. Material handling and storage syst MS layout configuration, Material handling equipm function, FMS data file, system reports plannin pulsetion and henefits	tem: Func ient. Comp	tions of the outer control
		pplication and benefits. •ibuted data processing in FMS		0 h
		processing in FMS: DBMS and their applications in		8 hours
distribute data base	d systems - Clampi	s in FMS –Integration of CAD and CAM - Part prog ng devices and fixtures data base. – features of industrial robots - robot cell design an	ramming i	n FMS, tool
UNIT-I		ip Technology	u control	8 hours
coding s Determin Just In Ti	ystem, M ing the be me and L	y: Part families, part classification and coding. Type achine cell design: The composite part concept, est machine arrangement, benefits of group technolo ean Production: Lean Production and Waste in Man automation, work involvement.	types of gy.	cell design.
UNIT-I	V Intro	oduction of FMS		8 hours
		mposition of FMS- hierarchy of computer control	-compute	
specificat Applicati	tion and so on of s turing dat	ssembly lines – FMS supervisory computer contro election – trends. imulation – model of FMS– simulation soft a systems – data flow – FMS database systems	ware – 1	imitation –
UNIT-V		luction Planning and control systems		8 hours
Production production control, inspection	on Plann on schedu inventory	ing and control systems: Aggregate Production Pl le, Material Requirements and Planning, capacity control, extensions of MRP CMM types: cor es - programming and operation-in cycle gauging	planning ntact and	d the master , shop floor non-contact
CO 1	1			K ₂ , K ₃
	Understa	and the components of flexible manufacturing system	11	K ₂ , K ₃
CO 2		ne concept of data-based management system for i and CAM	ntegration	K3

CO 3	Understand the concept of part family formation and cell design.K3				
CO 4 Understand the concept of automated material handling system		K4			
CO 5	CO 5 Understand the different module of MRP and CMM				
Text	books& Reference Books				
1.	1. Radhakrishnan P. and Subramanyan S., "CAD/CAM/CIM", Wiley Eastern Ltd., New				
	Age International Ltd., 1994.				
2.	Raouf, A. and Ben-Daya, M., Editors, "Flexible manufacturing systems:				
	recentdevelopment", Elsevier Science, 1995.				
3.	3. Groover M.P., "Automation, Production Systems and Computer Integrated				
	Manufacturing", Prentice Hall of India Pvt., New Delhi, 1996.				
4.	Kalpakjian, "Manufacturing Engineering and Technology", Addison-Wes	sley			
	Publishing Co., 1995.				

		M. TECH FIRST YEAR				
Cour	se Code	AMTME0220 L T P	Credit			
	se Title	Machine Vision 300	3			
	se objectiv					
1		the concepts of Physics behind Digital Image Processing.				
2		the Methods of Image Acquisition.				
3	Ų	pplying the different knowledge in different types image Processing.				
4		Developing knowledge of different types analysing the Captured Image.				
5	U	ng at the idea about Machine Vision Applications.				
	•					
		Course Contents / Syllabus				
UNIT	'-I I	NTRODUCTION	8 hours			
Block Machi Surfac	Diagram ar ne Vision Sy e – Thin Len		of Industrial t a Spherical			
UNIT		MAGE ACQUISITION – Lighting Parameters – Lighting Sources, Selection	10 hours			
Specif Interfa Compu	cations and ce Architect	pes and Selection – Machine Vision Lenses and Opt Selection – Imaging Sensors – CCD and CMOS, Spec ures – Analog and Digital Cameras –Digital Camera Interfac es, Specifications and Selection – Geometrical Image Formati n.	cifications – es – Camera			
UNIT	-III I	MAGE PROCESSING	8 hours			
Machi	ne Vision So	oftware – Fundamentals of Digital Image – Image Acquisiti	on Modes –			
Image Processing in Spatial and Frequency Domain - Point Operation, Thresholding,						
-		ng - Neighbourhood Operations, Image Smoothing and S	harpening –			
-		Sinary Morphology – Colour image processing.				
UNIT		MAGE ANALYSIS	8 hours			
		– Region Features, Shape and Size Features – Texture				
	-	and Classification – 3D Machine Vision Techniques – Decis				
		ACHINE VISION APPLICATIONS	8 hours			
Textile and S Survei	, Application		otics – Field ted Reality,			
CO 1	Explain	the concepts of Physics behind Digital Image Processing.	K3			
CO 2	Illustrate	the Methods of Image Acquisition.	K2			
CO 3	Apply th	e different knowledge in different types image Processing.	K3			
CO 4	1	knowledge of different types analysing the Captured Image.	K4			
CO 5	Impleme	nt at the idea about Machine Vision Applications.	K4			

Text books

1. Alexander Horn berg, "Hand Book of Machine Vision", Wiley-VCH, 2006.

2. Davies E.R., "Machine Vision Theory, Algorithms and Practicalities", Elsevier, 2005.

Reference Books

1. NelloZuech, "Understanding and Applying Machine Vision", Marcel Decker, 2000.

2. Bruce Bachelor and Frederick Waltz, "Intelligent Machine Vision Techniques, Implementations and Applications", Springer-Verlag, 2001.

3. Rafael C. Gonzales, Richard. E. Woods and Steven L. Eddins, "Digital Image Processing Using MATLAB", McGraw Hill Education, 2014.

4. Milan Sonka, Vaclav Hlavac and Roger Boyle, "Image Processing, Analysis, and Machine Vision", Cengage Learning, 2014.

5. Malay K. Pakhira, "Digital Image Processing and Pattern Recognition", PHI Learning, 2011.

6. Chanda B. and Dutta Majumder D., "Digital Image Processing and Analysis", PHI Learning, 2011.

M. TECH FIRST YEAR							
Course	Code	AMTME0221 L T P	Credit				
Course		Rapid Manufacturing & Tooling 3 0 0	3				
Course							
1	Able to know the fundamentals of RP Systems & its evolution and the Process in RP and association of RP Systems with 3D modelling & Mesh						
2	Able to know the RP Systems, Process, Materials & Classifications						
3	Able to know and working with Mesh File & their formats like STL format,						
	format, OBJ formats. Conversion to Mesh files, their properties, operations,						
	storage, inspections & defects						
4	Able to	know the applications of RP Systems in various Fields					
		Course Contents / Syllabus					
UNIT-I	Ι	Introduction:	4 hours				
Historical	l Develop	oments, Fundamentals of RP Systems and its Classification	on different				
		totyping Process Chains, 3D Modelling and Mesh Gene	eration, Data				
	I	ansmission.	1				
UNIT-I		RP Systems:	12 hours				
		Based Rapid Prototyping systems: SLA, Material Jetting,					
		Lapid Prototyping Systems: Laminated Object Manufacturing					
		Modelling Systems, Power Based Rapid Prototyping System	ms: Selective				
	-	ulti-Jet Fusion, Binder Jetting Systems.	0.1				
UNIT-I		RP Database & Design Optimization:	8 hours				
		Data Formats, STL Format, STL file problems, STL file re	epair, DIAM,				
<u> </u>	-	ation, Gcode for RP Systems	0 h				
UNIT-I		RP Applications: ies for Moulding, RP Applications in developing prototypes	8 hours				
		dical fields, Development of bone replacements and tiss					
		biological acceptability.					
Course			le to				
		nd the fundamentals of RP Technologies and process and in them	K1,K2				
CO 2	Understand the methodology to manufacture the products using RP K3, K4 technologies and study their applications, advantages and case studies						
	Understand the Design aspects and their respective challenges along K3 with the resolution for them						
CO 4	Understa	nd the various applications of various RP Systems with case Materials	K3,K4				
Text bo							
		ng: Principles an Applications: Chee Kai Chua, Kah Fai Leo	ng, Chu Sing				
	ve Manuf	acturing Technologies: 3D Printing, Rapid Prototyping, and I	Direct Digital				
		rent Stucker, David W. Rosen, Ian Gibson					
Referen	-						
-		uring: The Technologies and Applications of Rapid Prototypi	ng and Rapid				
Tooling	g: Pham, I	Duc, Dimov, S.S.					

- 2. Rapid Prototyping and Manufacturing: Fundamentals of Stereo Lithography: P. Jacobs
- 3. Rapid System Prototyping with FPGAs: Accelerating the Design Process: R.C. Cofer, Benjamin F. Harding
- 4. Rapid Prototyping of Digital Systems: Hamblen, James O., Hall, Tyson S., Furman, Michael D.

		M. TECH FIRST YEAR			
Course Code		AMTME0222 L T	' P	Credit	
Course Title		Hybrid Vehicle Technology 3 0		3	
Course o		i oi	-	_	
1		stand working of Electric Vehicles and recent trends.			
2		-how & aptitude towards future trends in Hybrid Electric V	<i>Vehicles</i>	3	
3		stand the various energy storage devices	•	,	
4	Understand the drive systems of hybrid vehicles				
5		stand energy management strategies			
	onder				
		Course Contents / Syllabus			
UNIT-I		Introduction:		hours	
		ybrid Electric Vehicles Conventional Vehicles. Hybrid E			
		ve-trains: Basic concept of electric traction, introduction ogies, power flow control in electric drive-train topolog			
analysis.	ισροιά	gies, power now control in cleane ante-train topolog.	ics, iuc		
UNIT-II	1	Electric Propulsion unit		12 hours	
		ion unit: Introduction to electric components used in l	nvbrid		
	-	uration and control of DC Motor drives, Configuration	-		
		drives, configuration and control of Permanent Mag			
		d control of Switch Reluctance Motor drives, drive system			
UNIT-II	I]	Energy Storage		8 hours	
Vehicles.	Battery	: Introduction to Energy Storage Requirements in Hy r, Fuel Cell, Super Capacitor and Flywheel based ener ration of different energy storage devices.			
UNIT-IV	-	Sizing the drive system		8 hours	
		system: Matching the electric machine and the internal	combus		
(ICE), Sizi	ing the	propulsion motor, sizing the power electronics, selecting munications, supporting sub systems.			
UNIT-V		Energy Management Strategies		8 hours	
		ment Strategies: Introduction to energy management	strateg		
hybrid and comparison manageme	d elec n of d ent strat	tric vehicles, classification of different energy mana lifferent energy management strategies, implementation regies. Case Studies: Design of a Hybrid Electric Vehicle (Vehicle (BEV).	gement issues	strategies, of energy	
Course o	outcon	ne: After completion of this course students will be	able to)	
CO 1		op the electric propulsion unit and its control for ation of electric vehicles.	K1,K2	2	
CO 2	Analy	ze different power converter topology used for electric e application.	K3, K4	4	
CO 3	Identify the principles of energy storage in hybrid vehicles		K3, K4, K5		
CO 4	Analy	ze the drive systems sizing.	K3,K4	L	
CO5	Devel	op the strategies for engine management.	K4		
Text boo	ks				

Iqbal Hussein, Electric and Hybrid Vehicles: Design Fundamentals, CRC Press, 2003 Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004

Reference Books

James Larminie, John Lowry, Electric Vehicle Technology Explained, Wiley, 2003 Chris Mi, M. Abul Masrur, David Wenzhong Gao, Hybrid Electric Vehicles: Principles and Applications with Practical Perspectives, John Wiley & Sons Ltd., 2011