NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)



Affiliated to

DR. A.P.J. ABDUL KALAM TECHNICAL UNIVERSITY UTTAR PRADESH, LUCKNOW



Evaluation Scheme & Syllabus

For

Minor Degree / Specialization

in

E-mobility

School of Mechanical Engineering

(Effective from the Session: 2022-23)

NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

Minor Degree / Specialization E-mobility

EVALUATION SCHEME

Sl.	Subject	Subject Name	P	Perio	d	Ev	alua	tion Scher	ne	En Seme		Total	Credit	
No.	Codes	Subject Name	L	T	P	AA	QZ	TOTAL	PS	TE	PE	Total	Crean	Sem
1	AMSEM0301	Modern Automotive Technology	3	0	0	25	25	50		100		150	3	III
2	AMSEM0401	Green Transportation Systems	3	0	0	25	25	50		100		150	3	IV
3	AMSEM0501	Smart vehicles	3	0	0	25	25	50		100		150	3	V
4	AMSEM0601	Power drives and systems	3	0	0	25	25	50		100		150	3	VI
5	AMSEM0701	Automotive Power Grids	3	0	0	25	25	50		100		150	3	VII
6	AMSEM0351	Modern Automotive Technology Lab	0	0	2				25		25	50	1	III
7	AMSEM0451	Green Transportation Systems Lab	0	0	2				25		25	50	1	IV
8	AMSEM0551	Power drives and systems Lab	0	0	2				25		25	50	1	V
9	AMSEM0751	Capstone Project	0	0	2				50		50	100	2	VII
		GRAND TOTAL										1000	20	

NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

Branch wise Minor Degree / Specialization Details

S.no.	Name of Minor Degree/Specialization	Streams/Branches of B.Tech. Programs whose students are eligible to opt for the Minor Degree	Streams/Branches of B.Tech. Programs whose students are eligible to opt for the Specialization
1	Artificial Intelligence and Machine Learning	All Branches except CSE and EC related Branches	CSE and EC related Branches
2	Data Science	All Branches except CSE and EC related Branches	CSE and EC related Branches
3	E-mobility	All Branches except ME related Branches	Only ME Branch
4	VLSI Design	All Branches except EC related Branches	Only EC Branch

NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

Guidelines for assessment of Minor Degree / Specialization Program

For Theory Paper

Intern	al (50)	External (100)
ASSIGNMENT (25)	QUIZ(25)	External (100)
5 Assignments of 5 marks each	5 Quiz papers of 5 marks each	Theory Examination will be
5 Assignments of 5 marks each	3 Quiz papers of 3 marks each	Conduct at the end of Semester

For Practical Paper

Internal (25)	External (25)
On the basis of continuous Assessment	Practical Examination will be Conduct at the end of Semester

Course Code	AMSEM0301	L	T	P	Credit
Course Title	Modern Automotive Technology	3	0	0	3
Course objectiv	/e:	•			
1. To understand	d Modern vehicles.				
2. To know about	at basics of Modern vehicles Technologies.				
3. To understand	d Energy Management.				
4. To describe a	bout Power Transmission & Control.				

5. To elaborate various Safety & Emission Norms.

Pre-requisites: Physics, Basic Electrical concepts, Basic Electronics

Course Contents / Syllabus

UNIT-I Introduction 8 hours

Introduction and need of modern technologies; Components of mechanical module in modern vehicles; Engine management system.

UNIT-II Modern vehicles Technologies

8 hours

Working Principle of Hybrid Electrical Vehicles technologies, Fuel Cell technology, Full Electric vehicles and types, solar power vehicles.

UNIT-III **Energy Management**

8 hours

Batteries; Electric machines Electric motors; Components of electrical & electronics module; energy consumption & efficiency.

UNIT-IV Power Transmission & Control

8 hours

Vehicle system module; Braking system; ABS components and Operations, power steering, suspension systems, Clutch and differential gear box

UNIT-V Safety & Emission Norms

8 hours

Emissions control techniques, Indian emissions standards and regulations, Safety measures; Diagnostic system for modern vehicles.

Course outcome:

CO 1	Understand the basic concepts of various systems used in automobile.	k2
CO 2	Understand the modern vehicle technologies and distinct types of vehicles.	k2
CO 3	Understand the principles and fundamentals of automotive electrical system and study their functions.	k2
CO 4	Understand the braking system and power transmission system- types & constructional features used in automobile.	k2
CO 5	Describe the principles and architecture of power and drive train and its components present in an automobile	k2

Text books:

- 1. "Modern Automotive Technology" by James E. Duffy
- 2. "Automobile Engineering", Dr. Kripal Singh.
- 3. "Automobile Engineering", R.B. Gupta, Satya Prakasan.
- 4. "Automobile Engineering", R.K. Rajput, Laxmi Publications (P) Ltd.

Reference Books:

- 1. Heldt P. M., "Automotive chassis", Chilton Co., New York.
- 2. Giles J.G., "Steering, Suspension and Tyres", Iliffe Book Co., London.
- 3. Heinz Heisler, "Advance vehicle Technology", Butterworth-Heinemann, 2002.

4. Newton a	and Steeds, "Motor vehicles", Life Publishers, 1985.
5. Crouse, V	V.H., Anglin, D.L.," Automotive Transmission and Power Trains construction", McGraw Hill,
Link: NPTI	EL/ YouTube/ Faculty Video Link:
Unit 1	https://www.youtube.com/watch?v=xCPINg7s1yY
Unit 2	https://www.youtube.com/watch?v=D-f0yVjYBRQ
Unit 3	https://www.youtube.com/watch?v=GeSY3oHHGAU
Unit 4	https://www.youtube.com/watch?v=uy9lZCdkQIM&list=PLD4ED2FAF3C155625
Unit 5	https://www.youtube.com/watch?v=HBPtdm9lErI

Course Code	AMSEM0401	L	T	P	Credit
Course Title	Green Transportation Systems	3	0	0	3

Course objective:

- 1. To understand Green Transportation Systems.
- 2. To know about basics of Modern Transport Planning
- 3. To understand Various Transportation Models
- 4. To describe about Transportation Strategies.
- 5. To elaborate various Green Transportation Infrastructures.

Pre-requisites:

Course Contents / Syllabus

UNIT-I Introduction 8 hours

Green Transportation: Introduction to Environmental Impact Assessment (EIA) and Transportation systems; Land-use plans, zoning schemes and provisions.

UNIT-II Modern Transport Planning

8 hours

Urban and regional transport planning Impacts on humans, flora and fauna, soil, water, air, climate and landscape, Airplanes, Railways, Metro, Ropeway, Tramways, Crane, Earth movers, Tractors, Commercial, Trucks & Buses.

UNIT-III Various Transportation Models

8 hours

Establishment of baseline conditions w.r.t soil, water and air quality; noise, air and water pollution modelling, Shipping, Bullet Trains, Magnetic Lavigation, Hyperloops.

UNIT-IV Transportation Strategies

8 hours

Modelling of impacts and scenario-based analysis; Assessment of potential project impacts including indirect, cumulative and synergistic impacts, Autonomous Vehicles, AI & ML applications, Fog security Systems.

UNIT-V Green Transportation Infrastructures

8 hours

Decision support systems for EIA of transport infrastructures; Abatement measures; Sustainable transportation systems, Hydrogen Fuel, Fuel Cells.

Course outcome:

CO 1	Understand the current transport systems, their sustainability consequences, and how	K2
	they can be transformed strategically to sustainability.	
CO 2	Describe in an overall way global sustainability challenges, policies and objectives that	K2
	affect the development potential of the transport sector.	
CO 3	Describe current and possible future passenger and goods transport modes and their life	K2
	cycles, and how they relate to strategic sustainable development	
CO 4	Describe current and possible future transport planning as a part of spatial planning for	K2
	urban and rural development, transport management/governance, integration of	
	different transport modes, and how they relate to strategic sustainable development.	
CO 5	Understand the various transportation strategies	K2

Text books:

- 1. Assessment & Decision Making for Sustainable Transport, European Conference of Ministers of Transport, OECD Publishing 2004.
- 2. Wood, C. and Wood, C., "Environmental Impact Assessment: A Comparative Review", Prentice Hall. 2002.
- 3. Petts, J., "Handbook of Environmental Impact Assessment", Blackwell Publishing. 1999

Reference Books:

- 1. Sucharov, L.J. and Baldasano, J.M., "Urban Transport and the Environment, Vol. II", Computational Mechanics Publications. 1996.
- 2. Zannetti P. (Ed.), "Environmental Modeling, Vol. I", Computational Mechanics Publication, Elsevier Applied Science. 1993.
- 3. Tumlin, Jeffrey (2012). Sustainable Transportation Planning: Tools for Creating Vibrant, Healthy and Resilient Communities. Wiley, Hoboken, NJ.

Unit 1	https://www.youtube.com/watch?v=2M8FZiKQ798
Unit 2	https://www.youtube.com/watch?v=OnjX0O9dPMc
Unit 3	https://www.youtube.com/watch?v=NwgjVFjmlws
Unit 4	https://www.youtube.com/watch?v=GJiaIcYuAlQ
Unit 5	https://www.youtube.com/watch?v=yDz5bRy7AgI

Course Tit	de	AMSEM0501	L	T	P	(Credit
Course III	le	Smart vehicles	3	0	0		3
Course	obj	ective:					
1. To ur	nders	stand Automated, Connected, and Intelligent Vehicles.					
2. To kr	now	about basics of Remote Sensing and Wireless Technology.					
3. To ur	nders	stand Wireless Networking and Connected Car Technology.					
4. To de	escri	be about Vehicle Prognostics Technology and Autonomous Ve	ehicle	es.			
5. To el	abor	ate various Troubleshooting and Maintenance of ADAS System	ms.				
Pre-req	uisi	tes: Physics, Basic Electrical concepts, Basic Electronics					
		Course Contents / Syllabus					
UNIT-I	[Introduction to Automated, Connected, and Intelligent	t			8	hour
		Vehicles					
		Electronics, Infotainment, Body, Chassis, and Power Train El					
		sted Systems, Basic Control System Theory, Overview of ECU	_			ept	
•		ysical Control Systems, Remote Sensing Technology, Wireles	s Ne	twork	s and		
Autono	my.						
UNIT-I	T	Domoto Consing and Wiveless Technology				10	hour
		Remote Sensing and Wireless Technology nar, LIDAR – Multiple Beam, Cameras & Night Vision, Mode	1.0		0 0		Hour
Basic N	etwa	Wireless Networking and Connected Car Technology					Hour
and Cel Review Vehicle	lular of C -to-V	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue.	orks nd O	to Of ther A	f Board Applica	2.16, d,	nour
and Cel Review Vehicle Wireles	lular of C -to-V s Se	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue.	orks nd O ructu	to Of ther A ire (V	f Board Applica	2.16, l, tions,	
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and Cel Review Vehicle Wireles UNIT-I Monitor Predicti	lular of C -to-V ss Sec IV ring ons,	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue.	orks nd O ructu icles	to Off ther A ire (V	f Board Applica 2I), d-of-L	2.16, d, ttions, 8	
and Cel Review Vehicle Wireles UNIT-I Monitor Predicti	lular of C -to-V s Sec [V ring ons, earni	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue. Vehicle Prognostics Technology and Autonomous Vehoof Vehicle Systems – Advanced OBD, Basic Maintenance FundaDAS Maintenance, Driverless Vehicle Technology, Artificia	orks nd O ructu icles	to Off ther A ire (V	f Board Applica 2I), d-of-L	2.16, d, ttions, 8 ife	hour
and Cel Review Vehicle Wireles UNIT-I Moniton Predicti Deep Lo	lular of C -to-V s Sec V	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue. Vehicle Prognostics Technology and Autonomous Vehoof Vehicle Systems – Advanced OBD, Basic Maintenance FundaDAS Maintenance, Driverless Vehicle Technology, Artificiang, Implementation Issues.	orks nd O ructu icles nction al Int	to Off ther Aure (V	f Board Applica 2I), d-of-L nce and	2.16, d, ttions, 8 ife	hour
and Cel Review Vehicle Wireles UNIT-I Monitor Predicti Deep Le	lular of Control of Sector	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks On-Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue. Vehicle Prognostics Technology and Autonomous Vehoof Vehicle Systems – Advanced OBD, Basic Maintenance Fundamentals, Navigation and Maintenance of ADAS Systems Troubleshooting and Maintenance of ADAS Systems	orks nd O ructu icles action al Int	to Off ther Aure (V	f Board Applica 2I), d-of-L nce and	2.16, dl, ditions, stions, sti	hour
and Cel Review Vehicle Wireles UNIT-I Monitor Predicti Deep Le UNIT-V	Iular of Control of Section V Modere Up	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks on Board Networks, Connectivity Fundamentals, Navigation at Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue. Vehicle Prognostics Technology and Autonomous Vehoof Vehicle Systems — Advanced OBD, Basic Maintenance Fundamentation Issues. Troubleshooting and Maintenance of ADAS Systems es and Self Calibration, Sensor Testing and Calibration, Reduced Control of Calibratic Calibratic Control of Ca	orks nd O ructu icles action al Int	to Off ther Aure (V	f Board Applica 2I), d-of-L nce and	2.16, dl, ditions, stions, sti	hour
and Cel Review Vehicle Wireles UNIT-I Monitor Predicti Deep Le UNIT-V Failure Softwar	lular of C -to-V ring ons, earni Mod re Up	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks on Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue. Vehicle Prognostics Technology and Autonomous Vehoof Vehicle Systems – Advanced OBD, Basic Maintenance FundaDAS Maintenance, Driverless Vehicle Technology, Artificiang, Implementation Issues. Troubleshooting and Maintenance of ADAS Systems es and Self Calibration, Sensor Testing and Calibration, Reduced or Sensor Senso	orks nd O ructu icles action al Int	to Off ther Aure (V	f Board Applica 2I), d-of-L nce and	2.16, dl, ditions, stions, sti	hour
and Cel Review Vehicle Wireles UNIT-I Monitor Predicti Deep Le UNIT-V Failure Softwar Military	lular of Control s Section IV ring ons, earni Mod re Up 7.	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks on Board Networks, Connectivity Fundamentals, Navigation a Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue. Vehicle Prognostics Technology and Autonomous Vehoof Vehicle Systems – Advanced OBD, Basic Maintenance FundaDAS Maintenance, Driverless Vehicle Technology, Artificiang, Implementation Issues. Troubleshooting and Maintenance of ADAS Systems es and Self Calibration, Sensor Testing and Calibration, Reduced or Sensor Senso	orks nd O ructu icles action al Int	to Off ther Aure (V	f Board Applica 2I), d-of-L nce and	2.16, dl, ditions, stions, sti	hour
and Cel Review Vehicle Wireles UNIT-I Monitor Predicti Deep Lo UNIT-V Failure Softwar Military Course	Iular of Control s Section IV ring ons, earni V Mod re Up	orking Concepts, Wireless Networking Fundamentals, IEEE80, Protocols and IP Addressing, Connection of On-Board Networks and IP Addressing, Connection of On-Board Networks (Connectivity Fundamentals, Navigation at Vehicle (V2V), Vehicle-to-Roadside (V2R), Vehicle-to-Infrast curity Issue. Vehicle Prognostics Technology and Autonomous Vehof Vehicle Systems – Advanced OBD, Basic Maintenance Funda ADAS Maintenance, Driverless Vehicle Technology, Artificiang, Implementation Issues. Troubleshooting and Maintenance of ADAS Systems es and Self Calibration, Sensor Testing and Calibration, Reduction and Maintenance, Trucking, Farming, Miningerades, Uber/Lyft Business Model, Trucking, Farming, Miningerades.	orks nd O ructu icles action al Int	to Off ther Aure (V	f Board Applica 2I), d-of-L nce and	2.16, dl, ditions, stions, sti	hour

Explain the use of different Remote Sensing and Wireless Technologies.

CO 3

K2, K3

CO 4	Analyze Vehicle Prognostics Technology and Autonomous Vehicles systems.	K3, K4
CO 5	Relevant Troubleshooting and Maintenance of ADAS Systems.	K2,
Text b	ooks:	
	o Vlacic, Michel Parent, Fumio Harashima, "Intelligent Vehicle Technologies Theory pplications" Boca Raton, CRC Press, 2001	
2. Hus	ain, I. "Electric and Hybrid Vehicles" Boca Raton, CRC Press, 2010.	
3.Stua	t Borlase 'Smart Grid: Infrastructure, Technology and Solutions', CRC Press 2012.	
Refere	nce Books:	
	fullett, Wireless Telecommunications Systems and Networks, Thomson – Delmar ng, ISNB#1-4018-8659-0, 2006	
Link:	NPTEL/ YouTube/ Faculty Video Link:	-
Unit 1	https://www.youtube.com/watch?v=HgF7E5q9sU4	-
Unit 2	https://www.youtube.com/watch?v=N49PzLDUIFQ	
Unit 3	https://www.youtube.com/watch?v=0FXHr1B8H7M	
Unit 4	https://www.youtube.com/watch?v=gEy91PGGLR0	
Unit 5	https://www.youtube.com/watch?v=EiWl5PAtfYA	-

Course Code	AMSEM0601	L	T	P	Credit
Course Title	Power drives and systems	3	0	0	3

Course objective:

- 1. To understand Automated, Connected, and Intelligent Vehicles.
- 2. To know about basics of Remote Sensing and Wireless Technology.
- 3. To understand Wireless Networking and Connected Car Technology.
- 4. To describe about Vehicle Prognostics Technology and Autonomous Vehicles.
- 5. To elaborate various Troubleshooting and Maintenance of ADAS Systems.

Pre-requisites: Physics, Basic Electrical concepts, Basic Electronics

Course Contents / Syllabus

UNIT-I Introduction 8 hours

Power Drives: Dynamics of Electric Drives: Fundamentals of torque equation, Speed torque convention and multi-quadrant operation, components of load torques

UNIT-II Power Drive Classifications

8 hours

Classification of load torques steady state stability. Load equation, Speed control and drive classification and close loop control of drives.

UNIT-III Various Power Drives

8 hours

DC motor Drives-Modelling of DC machines. Steady state characteristics with armature and speed control, Phase controlled DC motor drives, Chopper controlled DC motor drives.

UNIT-IV Various Power Drive Control Systems

8 hours

Poly-phase induction machines- Dynamic modelling of induction machines. Small signal equations, control characteristics of induction machines. Phase-controlled induction machines, Stator voltage control, Slip energy recovery scheme, frequency control and vector control of induction motor drives.

UNIT-V Power Machines

8 hours

Traction motor: Starting, Speed-Time characteristics, Braking, Traction motors used in practice. Industrial Drives-Digital Control of Electric Drives, Stepper motor, Servo motor, Solar drive, BLDC drive, PMSM drive, SRM drive and their specific applications.

Course outcome:

CO 1	Model and simulate electric drive systems	K2
CO 2	Design modulation strategies of power electronics converters, for drives application	K2
CO 3	Design appropriate current/voltage regulators for electric drives	K2
CO 4	Select and implement the drives for Industrial Process	K2
CO 5	Implement various variable speed drives in Electrical Energy Conversion System	K2

Text books:

- 1. G.K, Dubey, "Power semiconductor controlled Drives", Prentice Hall international, New Jersey, 1989.
- 2. R.Krishanam, "Electric motor drives modeling, analysis and control", PHI-India-2009
- 3. G. K. Dubey, "Fundamentals of electric Drives, Narosa Publishing House", 2nd edition, 2011.

Reference Books:

- 1. W. Leonhard, "Control of Electrical drives", Springer, 3rd edition, 2001.
- 2. P.C. Krause –, "Analysis of Electric Machine", Wiley-IEEE press 3rdedition.
- 3. K. Bose, "Modern Power Electronics and AC Drives", Prentice Hall publication, 1st edition, 2001.

Link: NP	ΓΕL/ YouTube/ Faculty Video Link:
Unit 1	https://www.youtube.com/watch?v=btNSMMednG0
Unit 2	https://www.youtube.com/watch?v=E8f_h_6DIZc
Unit 3	https://www.youtube.com/watch?v=EaENkSSUK-k
Unit 4	https://www.youtube.com/watch?v=1AT1yuQ9awM&list=PLFW6lRTa1g83sIfVY1p1xGqPGYUmXyahx
Unit 5	https://www.youtube.com/watch?v=L6bq5U9tVt0

	AMSEM0701	L	T	P	Credit
Course Title	Automotive Power Grids	3	0	0	3
Course object	ive:			L	
1. To understa	nd hybrid electric vehicle				
2. To know ab	out basics of electric drives				
To understa	nd concept of energy storage				
	about Energy management systems				
	e various Mobility and connectors				
Pre-requisites	: Physics, Basic Electrical concepts, Basic Electronics				
	Course Contents / Syllabus		1		
UNIT-I	Introduction to Hybrid Electric Vehicle				8 hour
	eventional Vehicle: Introduction to Hybrid Electric Vehicles:	Гуреs	of EV	s,	
Hybrid Electri	c Drivetrain, Tractive effort in normal driving				
UNIT-II	Electric Drives				10 hour
Energy consur	nption Concept of Hybrid Electric Drive Trains, Architecture	of Hyl	orid E	lectric 1	Drive Trains
•	Electric Drive Trains, Parallel hybrid electric drive tr			-	•
_	and control of DC Motor drives, Induction Motor drives, Po	erman	ent M	agnet N	Motor drive
switched reluc					0.1
UNIT-III	Energy Storage		1	1	8 hour
	Energy Storage Requirements in Hybrid and Electric Vehicle		•		
•	s, Fuel Cell based energy storage and its analysis, Hybridizage the drive system, Design of Hybrid Electric Vehicle and Plug				0.
UNIT-IV	Energy Management System	3-111 151		Venici	8 hour
	ement Strategies, Automotive networking and communication	. EV	chargi	ng stan	
			_	_	
$\cup \angle V$, $V \angle D$, $V \angle$	2H. Business: E-mobility business, electrification challenges, I	Justiic			y business,
	2H. Business: E-mobility business, electrification challenges, lachallenges.	Justife			y business,
electrification		- Justine			
electrification UNIT-V	challenges.			Perspe	8 hour
electrification UNIT-V Connected Mo	challenges. Mobility and Connectors	n Roa	dmap	_	8 hour
electrification UNIT-V Connected Mo EVs in infrasti	challenges. Mobility and Connectors bility and Autonomous Mobility- case study E-mobility India	n Roa	dmap f EVs	. Conne	8 hour ctive. Policy ectors- Type
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electrification UNIT-V Connected Mo EVs in infrastrof EV charging America, CCS	challenges. Mobility and Connectors	n Roa ions o	dmap f EVs V Pluş	. Conne g Stand	8 hour ctive. Policy ectors- Type ards in Nort
electrification UNIT-V Connected Mo EVs in infrastr of EV charging America, CCS	challenges. Mobility and Connectors bility and Autonomous Mobility- case study E-mobility India ucture system, integration of EVs in smart grid, social dimens g connector, North American EV Plug Standards, DC Fast Cha (Combined Charging System), CHAdeMO, Tesla, European me:	n Roa ions o	dmap f EVs V Pluş	. Conne g Stand	8 hour ctive. Policy ectors- Type ards in Nort
electrification UNIT-V Connected Mo EVs in infrastr of EV chargin America, CCS Course outco CO 1 An	challenges. Mobility and Connectors bility and Autonomous Mobility- case study E-mobility India ucture system, integration of EVs in smart grid, social dimense connector, North American EV Plug Standards, DC Fast Char (Combined Charging System), CHAdeMO, Tesla, European me: alyze the grid system in hybrid electric Vehicles.	n Roa ions o	dmap f EVs V Pluş	. Conne g Stand	8 hour ctive. Policy ectors- Type ards in Nort
electrification UNIT-V Connected Mo EVs in infrastr of EV chargin America, CCS Course outco CO 1 An CO 2 Eva	Mobility and Connectors bility and Autonomous Mobility- case study E-mobility India aucture system, integration of EVs in smart grid, social dimenses connector, North American EV Plug Standards, DC Fast Cha (Combined Charging System), CHAdeMO, Tesla, European alyze the grid system in hybrid electric Vehicles. Calvate concept of electric drives	n Roa ions o	dmap f EVs V Pluş	. Conne g Stand	8 hour ctive. Policy ectors- Type ards in Nort
electrification UNIT-V Connected Mo EVs in infrastr of EV chargin America, CCS Course outco CO 1 An CO 2 Eva CO 3 Exp	challenges. Mobility and Connectors bility and Autonomous Mobility- case study E-mobility India aucture system, integration of EVs in smart grid, social dimenses connector, North American EV Plug Standards, DC Fast Character (Combined Charging System), CHAdeMO, Tesla, European me: alyze the grid system in hybrid electric Vehicles. aluate concept of electric drives blain the use of different energy storages	n Roa ions o	dmap f EVs V Pluş	. Conne g Stand	8 hour ctive. Policy ectors- Type ards in Nort K ₁ , K ₂ K ₃ , K ₄ K ₂ , K ₃
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Reference B	Reference Books:					
	1. Larminie, James, and John Lowry, "Electric Vehicle Technology Explained" John Wiley					
and Sons, 20	12					
2. Sheldon S	S. Williamson, "Energy Management Strategies for Electric and Plug-in Hybrid					
3. Electric V	Vehicles", Springer, 2013					
Link: NPTE	Link: NPTEL/ YouTube/ Faculty Video Link:					
Unit 1	Init 1 https://www.youtube.com/watch?v=opvKyJ3DVJI					
Unit 2	https://www.youtube.com/watch?v=1AT1yuQ9awM&list=PLFW6lRTa1g83sIfVY1p1xGqPGYUmXyahx					
Unit 3	· · · · · · · · · · · · · · · · · · ·					
Unit 4	https://www.youtube.com/watch?v=JABjhJHX8Tc					
Unit 5	https://www.youtube.com/watch?v=ASU5nT3cTfs					

Course Code	AMSEM0351	L	T	P	Credit
Course Title	Modern Automotive Technology Lab	0	0	2	1

Course objective:

Students will be studying the experiments based on Modern Automotive Technology systems

Suggested list of Experiment Perform Ten experiment from the list of Experiment			
S. No.	Name of Experiments		
1	To Study Engine control units in modern Automobile systems		
2	To Study Engine management techniques		
3	To Study Engine cooling system of modern vehicles		
4	To Study hybrid electric vehicle		
5	To Study fuel cell technology		
6	To Study solar power vehicles		
7	To Study electric motors		
8	To Study energy consumption and efficiency		
9	Draw a flowchart of ABS components		
10	To Study manual clutch and gear box		
11	To Study power steering		
12	To Study suspension systems		

Course outcome:

CO 1	Understand the concept of Engine control	K2
CO 2	Understand the concept of Engine management	K2
CO 3	Understand the concept of Engine cooling system	K2
CO 4	Understand the concept of fuel cell technology	K2
CO 5	Understand the concept of electric motors	K2

Link: NPTEL/ YouTube/ Faculty Video Link:

1.	https://www.youtube.com/watch?v=dxv579W2G2c
2.	https://www.youtube.com/watch?v=HgwhvfKcMMw

Course Code	AMSEM0451	L	T	P	Credit
Course Title	Green Transportation Systems Lab	0	0	2	1

Course objective:
Students will be studying the experiments based on Green Transportation Systems.

Suggested list of Experiment Perform Ten experiment from the list of Experiment S. No. Name of Experiments To Study Environmental Impact Assessment (EIA) model for automobiles. To Study Land-use plans, zoning schemes. To Study Urban and regional transport planning Impacts on humans To Study Urban and regional transport planning Impacts on Trucks & Buses To Study Urban and regional transport planning Impacts on Trucks & Buses To Study Urban and regional transport planning Impacts on Trucks & Buses To Study Extablishment of baseline conditions w.r.t soil, water and air quality. To Study Magnetic Levitation. To Study Modelling of impacts and scenario-based analysis. To Study Modelling of impacts and scenario-based analysis. To Study Fog security Systems To Study Fog security Systems To Study Sustainable transportation systems To Study Decision support systems for EIA of transport infrastructures. Course outcome: CO 1 Understand the concept of Land-use plans, zoning schemes CO 2 Understand the concept of Environmental Impact Assessment (EIA) model for automobiles CO 3 Understand the concept of Magnetic Levitation. K2 CO 4 Understand the concept of Bullet Trains model. CO 5 Understand the concept of Fog security Systems Link: NPTEL/ YouTube/ Faculty Video Link:	Pre-requ	isites	: Student know the concept of Automobiles and systems						
To Study Environmental Impact Assessment (EIA) model for automobiles. To Study Land-use plans, zoning schemes. To Study Urban and regional transport planning Impacts on humans To Study Urban and regional transport planning Impacts on Trucks & Buses To Study Establishment of baseline conditions w.r.t soil, water and air quality. To Study Magnetic Levitation. To Study Bullet Trains model. To Study Modelling of impacts and scenario-based analysis. To Study Assessment of potential project impacts To Study Fog security Systems To Study Decision support systems for EIA of transport infrastructures. Course outcome: CO 1 Understand the concept of Land-use plans, zoning schemes CO 2 Understand the concept of Environmental Impact Assessment (EIA) model for automobiles CO 3 Understand the concept of Magnetic Levitation. CO 4 Understand the concept of Bullet Trains model. E2 CO 5 Understand the concept of Fog security Systems Link: NPTEL/ YouTube/ Faculty Video Link: I. https://www.youtube.com/watch?v=yDz5bRy7AgI		Sug	gested list of Experiment Perform Ten experiment from the list of Experiment						
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To Study Urban and regional transport planning Impacts on Trucks & Buses To Study Establishment of baseline conditions w.r.t soil, water and air quality. To Study Magnetic Levitation. To Study Bullet Trains model. To Study Modelling of impacts and scenario-based analysis. To Study Assessment of potential project impacts To Study Fog security Systems To Study Sustainable transportation systems To Study Decision support systems for EIA of transport infrastructures. Course outcome: CO 1 Understand the concept of Land-use plans, zoning schemes CO 2 Understand the concept of Environmental Impact Assessment (EIA) model for automobiles CO 3 Understand the concept of Magnetic Levitation. CO 4 Understand the concept of Bullet Trains model. CO 5 Understand the concept of Fog security Systems Link: NPTEL/ YouTube/ Faculty Video Link: https://www.youtube.com/watch?v=yDz5bRy7AgI									
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To Study Sustainable transportation systems To Study Decision support systems for EIA of transport infrastructures. Course outcome: CO 1 Understand the concept of Land-use plans, zoning schemes	9		To Study Assessment of potential project impacts						
To Study Decision support systems for EIA of transport infrastructures. Course outcome: CO 1 Understand the concept of Land-use plans, zoning schemes	10		To Study Fog security Systems						
Course outcome: CO 1 Understand the concept of Land-use plans, zoning schemes	11		To Study Sustainable transportation systems						
CO 1 Understand the concept of Land-use plans, zoning schemes CO 2 Understand the concept of Environmental Impact Assessment (EIA) model for automobiles CO 3 Understand the concept of Magnetic Levitation. CO 4 Understand the concept of Bullet Trains model. CO 5 Understand the concept of Fog security Systems Link: NPTEL/ YouTube/ Faculty Video Link: https://www.youtube.com/watch?v=yDz5bRy7AgI	12		To Study Decision support systems for EIA of transport infrastructures.						
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CO 4 Understand the concept of Bullet Trains model. CO 5 Understand the concept of Fog security Systems K2 Link: NPTEL/ YouTube/ Faculty Video Link: https://www.youtube.com/watch?v=yDz5bRy7AgI	CO 2								
CO 5 Understand the concept of Fog security Systems Link: NPTEL/ YouTube/ Faculty Video Link: https://www.youtube.com/watch?v=yDz5bRy7AgI	CO 3	Uno	derstand the concept of Magnetic Levitation.						
Link: NPTEL/ YouTube/ Faculty Video Link: 1. https://www.youtube.com/watch?v=yDz5bRy7AgI	CO 4	Uno	nderstand the concept of Bullet Trains model.						
1. https://www.youtube.com/watch?v=yDz5bRy7AgI	CO 5	Uno	Understand the concept of Fog security Systems K2						
, , , , , , , , , , , , , , , , , , ,	Link: NF	TEL/	YouTube/ Faculty Video Link:						
2 https://www.voutube.com/world-2v. pDwgmNvIIVI-V	1.		nttps://www.youtube.com/watch?v=yDz5bRy7AgI						
L. nups://www.youtube.com/watcn/v=pbweminvHvkY	2.		nttps://www.youtube.com/watch?v=pBwemNvHVkY						

Course Co	de AMSEM0551		L	T	P	Credit			
Course Ti	e Power drives and s	ystems Lab	0	0	2	1			
Course ob	ective:		1		I				
Students w	ll be studying the experir	ments based on Power drives a	and systems						
Pre-requis	tes: Student know the c	concept of Automobiles and	systems						
	uggested list of Experir	nent Perform Ten experim	ent from the lis	t of Ex	perime	ent			
S. No.									
1	To Study 1-phase Half & Full Controlled Converter.								
2	To study Characteris	To study Characteristics of 1-phase Cycloconverter							
3	To study the constru	To study the construction of a three-phase induction motor with the help of a model.							
4	•	To study about the starters of three phase induction motors							
5	, , ,	To study about the power modulator & control unit.							
6		To perform the Speed control of DC shunt Motor by Armature control.							
7		To Start DC shunt motor by using three-point starter							
8	1	To obtain the Speed control of DC shunt Motor by Field control.							
9		To study about the detailed structure of wind power station							
10		To study about Traction motor: Starting, Speed-Time characteristics							
11		To study about Poly-phase induction machines							
12	To study about Chor	pper controlled DC motor dri	ives						
Course ou	aoma.								
Course ou	come:								
CO 1	Understand the concept of	of Full Controlled Converter				K2			
CO 2	derstand the concept of Characteristics of 1-phase Cycloconverter K2								
CO 3	Understand the concept of Traction motor: Starting, Speed-Time characteristics				K2				

K2

K2

Understand the concept of Poly-phase induction machines

https://www.youtube.com/watch?v=mPJxo_RnlFE

https://www.youtube.com/watch?v=DBvCP-LL-mE

Link: NPTEL/ YouTube/ Faculty Video Link:

Understand the concept of Chopper controlled DC motor drives

CO 4

CO 5

1. 2